

Minimal supersolutions for BSDEs with singular terminal condition and application to optimal position targeting

T. Kruse^a, A. Popier^{b,*}

^a University of Duisburg–Essen, Thea-Leymann-Str. 9, 45127 Essen, Germany

^b Laboratoire Manceau de Mathématiques, Université du Maine, Avenue Olivier Messiaen, 72085 Le Mans, Cedex 9, France

Received 17 April 2015; received in revised form 9 December 2015; accepted 23 February 2016

Available online 9 March 2016

Abstract

We study the existence of a minimal supersolution for backward stochastic differential equations when the terminal data can take the value $+\infty$ with positive probability. We deal with equations on a general filtered probability space and with generators satisfying a general monotonicity assumption. With this minimal supersolution we then solve an optimal stochastic control problem related to portfolio liquidation problems. We generalize the existing results in three directions: firstly there is no assumption on the underlying filtration (except completeness and quasi-left continuity), secondly we relax the terminal liquidation constraint and finally the time horizon can be random.

© 2016 Elsevier B.V. All rights reserved.

MSC: 60H10; 93E20; 91G80

Keywords: Backward stochastic differential equations; Singular terminal condition; Stochastic control with constraints

0. Introduction

This paper is devoted to the study of backward stochastic differential equations (BSDEs) with *singular* terminal condition. We adopt from [28,29] the notion of a weak (super) solution (Y, ψ, M) to a BSDE of the following form

$$dY_t = -f(t, Y_t, \psi_t)dt + \int_{\mathcal{Z}} \psi_t(z) \tilde{\pi}(dz, dt) + dM_t, \quad (1)$$

* Corresponding author.

E-mail addresses: thomas.kruse@uni-due.de (T. Kruse), alexandre.popier@univ-lemans.fr (A. Popier).

where $\tilde{\pi}$ is a compensated Poisson random measure on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ with a filtration $\mathbb{F} = (\mathcal{F}_t)_{t \geq 0}$. The filtration \mathbb{F} is supposed to be complete and right continuous. In particular, it can support a Brownian motion orthogonal to $\tilde{\pi}$. The solution component M is required to be a local martingale orthogonal to $\tilde{\pi}$. The function $f : \Omega \times \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R}^d \rightarrow \mathbb{R}$ is called the *driver* (or *generator*) of the BSDE. The particularity here is that we allow the *terminal condition* ξ to be *singular*: for a stopping time τ , the random variable ξ is \mathcal{F}_τ -measurable and takes the value $+\infty$ with positive probability.

In our first main result ([Theorem 1](#)) we establish existence of a *minimal* weak supersolution to (1). This supersolution is constructed via approximation from below. For each $L > 0$ we consider a truncated version of (1) with terminal condition $\xi \wedge L$. We impose that the driver f satisfies a monotonicity assumption in the y -variable and is Lipschitz continuous with respect to ψ . Then existence, uniqueness and comparison results for a solution (Y^L, ψ^L, M^L) to the truncated BSDE can be deduced from [23], where the theory of BSDEs with a monotone driver in a general filtration has been developed. We obtain the minimal supersolution (Y, ψ, M) with singular terminal condition by passing to the limit $L \rightarrow \infty$. The crucial task is to establish suitable a priori estimates for Y^L guaranteeing that when passing to the limit the solution Y does not explode before time τ . To this end, the generator f cannot be Lipschitz continuous w.r.t. y . Hence we impose that f is monotone and decreases at least polynomially with random coefficient in the y -variable. In the case where τ is deterministic this condition suffices to ensure boundedness of Y^L . When τ is random, we restrict attention to first exit of diffusions from a regular set.

BSDEs with singular terminal condition were already studied in [3,28] for deterministic terminal time (see also [12] for a treatise on BSPDEs), and in [29] for a random terminal time. Let us briefly outline in which directions our findings generalize some results from these papers.

- *General driver f .* Indeed, in the previously mentioned papers f is assumed to be a polynomial function of y (plus possibly a particular bounded from above function of ψ in [12]). Here f is supposed to be only bounded from above by a polynomial function w.r.t. y . The fact that we only assume here that f is Lipschitz continuous with respect to ψ but not necessarily bounded, requires to derive new a priori estimates for the family of solutions (Y^L) . Moreover as in [3], the generator can be *singular* in the sense that the process $f_t^0 = f(t, 0, 0)$ can explode at time τ . We only impose an integrability condition on f^0 which is weaker than the condition in [3]. This weaker integrability condition and the occurrence of jumps imply that the convergence of the approximating sequence $(Y^L)_{L>0}$ has to be handled more carefully (see in particular the proof of [Proposition 3](#) where technical details are postponed in the [Appendix](#)). BSDEs where the generator possesses a singularity in the time variable were studied in [19,18] to solve utility maximization problems with random horizon.
- *General filtration \mathbb{F} .* Moreover, compared to the papers [3,28,29], we do not restrict attention to a filtration generated by Brownian and Poisson noise. Here the filtration \mathbb{F} satisfies only the standard assumptions (completeness and right-continuity). Hence the additional local martingale part M appears in the BSDE and has to be controlled when we let L go to $+\infty$. The quasi left-continuity condition on \mathbb{F} will be imposed only to ensure the lower semi-continuity of Y at time τ : $\liminf_{t \rightarrow \tau} Y_t \geq \xi$.
- *Random terminal time τ .* To our best knowledge, [29] is the only paper that deals with a singular terminal condition at a random time τ . In this work, the generator f is equal to $f(y) = -y|y|^{q-1}$ for some $q > 1$ and the filtration is generated by a Brownian motion. When the terminal time is random, the derivation of the a priori estimate for the sequence Y^L

is more involved than in the deterministic case. For a general random time τ , we show that the limit process Y may be infinite before time τ . For this reason, we consider the first exit time of a continuous diffusion from a regular set and our estimate is a generalization of the Keller–Osseman inequality.

We also note that our results can be extended to the case where the driver is additionally a Lipschitz continuous function of a variable Z , which represents the integrand in the martingale representation w.r.t. a Brownian motion (cf. Remark 5).

Since the seminal paper by Pardoux and Peng [25] BSDEs have proved to be a powerful tool to solve stochastic optimal control problems (see e.g. the survey article [7] or the book [26]). In the second part of the paper we use the notion of weak supersolutions to provide a purely probabilistic solution of a stochastic control problem with a terminal constraint on the controlled process. More precisely, we consider the problem of minimizing the cost functional¹

$$J(X) = \mathbb{E} \left[\int_0^\tau \left(\eta_s |\alpha_s|^p + \gamma_s |X_s|^p + \int_{\mathcal{Z}} \lambda_s(z) |\beta_s(z)|^p \mu(dz) \right) ds + \xi |X_\tau|^p \right] \quad (2)$$

over all progressively measurable processes X that satisfy the dynamics

$$X_s = x + \int_0^s \alpha_u du + \int_0^s \int_{\mathcal{Z}} \beta_u(z) \pi(dz, du).$$

Here $p > 1$ and the processes η , γ and λ are non negative progressively measurable. Again the \mathcal{F}_τ -measurable random variable ξ takes the value ∞ with positive probability. This singularity imposes the terminal state constraint on the set of strategies. Indeed, any strategy X that does not satisfy this terminal constraint creates infinite costs. In particular, such a strategy cannot be optimal if there exists some strategy that creates finite costs (which will always be the case under the assumptions that we impose). In the cases where τ is deterministic or a first exit time, we characterize optimal strategies and the value function of this control problem with the BSDE

$$dY_t = (p-1) \frac{Y_t^q}{\eta_t^{q-1}} dt + \Theta(t, Y_t, \psi_t) dt - \gamma_t dt + \int_{\mathcal{Z}} \psi_t(z) \tilde{\pi}(dz, dt) + dM_t \quad (3)$$

with $\liminf_{t \rightarrow \tau} Y_t \geq \xi$. Here $q > 1$ is the Hölder conjugate of p and Θ is a Lipschitz continuous function (see (24) for the precise definition). We provide sufficient conditions on the coefficient processes η , γ and λ such that Theorem 1 ensures existence of a minimal weak supersolution to (3) and carry out a verification that is based on a penalization argument.

The analysis of optimal control problems with state constraints on the terminal value is motivated by models of optimal portfolio liquidation under stochastic price impact. The traditional assumption that all trades can be settled without impact on market dynamics is not always appropriate when investors need to close large positions over short time periods. In recent years models of optimal portfolio liquidation have been widely developed, see, e.g. [1,2,8,10,15], or [22], among many others.

Variants of the position targeting problem (2) have been studied in [3,4,31,12] or [13]. In this framework the state process X denotes the agent's position in the financial market. She has two means to control her position. At each point in time t she can trade in the primary venue at a rate α_t which generates costs $\eta_t |\alpha_t|^p$ incurred by the stochastic price impact parameter η_t .

¹ We define $0 \cdot \infty := 0$.

Moreover, she can submit passive orders to a secondary venue (“dark pool”). These orders get executed at the jump times of the Poisson random measure π and generate so called slippage costs $\int_{\mathcal{Z}} \lambda_t(z) |\beta_t(z)|^p \mu(dz)$. We refer to [22] for a more detailed discussion. The term $\gamma_t |X_t|^p$ can be understood as a measure of risk associated to the open position. $J(X)$ thus represents the overall expected costs for closing an initial position x over the time period $[0, \tau]$ using strategy X .

Our approach allows to incorporate some novel features into optimal liquidation models. First, we do not impose any assumption on the filtration (except quasi-left continuity). For the financial model, this means that the noise is not necessarily generated by a Brownian motion. Moreover, the liquidation constraint is relaxed in the following way. Instead of enforcing the condition $X_\tau = 0$ a.s., that is the position has to be closed imperatively, our model is flexible enough to allow for a specification of a set of market scenarios $\mathcal{S} \subset \mathcal{F}_\tau$ where liquidation is mandatory: $X_\tau \mathbf{1}_{\mathcal{S}} = 0$. On the complement \mathcal{S}^c a penalization depending on the remaining position size can be implemented. This terminal constraint is described by the \mathcal{F}_τ -measurable non negative random variable ξ such that $\mathcal{S} = \{\xi = +\infty\}$. Thus for a binding liquidation $X_\tau = 0$, we take $\xi = +\infty$ a.s. For excepted scenarios, we can consider $\xi = \infty \mathbf{1}_{\mathcal{S}}$ with for example $\mathcal{S} = \{\max_{t \in [0, T]} \eta_t \leq H\}$ or $\mathcal{S} = \{\int_0^T \eta_t dt \leq H\}$ for a given threshold $H > 0$. This means that liquidation is only mandatory if the maximal price impact (or the average price impact) is small enough throughout the liquidation period. If the illiquidity of the market is too high, the trader has not obligatorily to close his position. Finally, our model allows for a random time horizon τ . For example, one can consider *price-sensitive* liquidation periods where the position has to be closed before the first time when the unaffected market price S (a diffusion) falls below some threshold level $K > 0$, i.e. $\tau = \inf\{t \geq 0 | S_t \leq K\}$.

The paper is decomposed as follows. In Section 1, we give the mathematical setting and present the main results concerning the BSDE (1). The set of assumptions will differ in the two cases τ deterministic (Theorem 1) and τ random (Theorem 2). We construct a supersolution of the BSDE (1) using truncation arguments as in [28] or [3] and we prove that this solution is minimal. As mentioned before the main difficulties are to control the sequence of solutions for the truncated BSDE (see Propositions 2 and 6) and to prove the convergence of the approximating sequence. In Section 2 we use the previous results to obtain a minimal supersolution for BSDE (3) and we verify that this solution gives the value function and an optimal control for the optimal position targeting problem (Theorem 3).

1. Minimal supersolutions for the singular BSDE

1.1. Setting and notation

We consider a filtered probability space $(\Omega, \mathcal{F}, \mathbb{P}, \mathbb{F} = (\mathcal{F}_t)_{t \geq 0})$. The filtration is assumed to be complete and right continuous. Moreover, we assume that \mathbb{F} is quasi-left continuous, which means that for every sequence (τ_n) of \mathbb{F} stopping times such that $\tau_n \nearrow \tilde{\tau}$ for some stopping time $\tilde{\tau}$ we have $\bigvee_{n \in \mathbb{N}} \mathcal{F}_{\tau_n} = \mathcal{F}_{\tilde{\tau}}$. We assume that $(\Omega, \mathcal{F}, \mathbb{P}, \mathbb{F} = (\mathcal{F}_t)_{t \geq 0})$ supports a Poisson random measure π with intensity $\mu(dz)dt$ on the space $\mathcal{Z} \subset \mathbb{R}^d \setminus \{0\}$. The measure μ is σ -finite on \mathcal{Z} such that

$$\int_{\mathcal{Z}} (1 \wedge |z|^2) \mu(dz) < +\infty.$$

By \mathcal{P} we denote the predictable σ -field on $\Omega \times \mathbb{R}_+$. We set $\tilde{\mathcal{P}} = \mathcal{P} \otimes \mathcal{B}(\mathcal{Z})$ where $\mathcal{B}(\mathcal{Z})$ is the Borelian σ -field on \mathcal{Z} . On $\tilde{\Omega} = \Omega \times [0, T] \times \mathcal{Z}$, a function that is $\tilde{\mathcal{P}}$ -measurable, is called

predictable. $G_{\text{loc}}(\pi)$ is the set of $\tilde{\mathcal{P}}$ -measurable functions ψ on $\tilde{\Omega}$ such that for any $t \geq 0$ a.s.

$$\int_0^t \int_{\mathcal{Z}} (|\psi_s(z)|^2 \wedge |\psi_s(z)|) \mu(dz) ds < +\infty.$$

For any stopping time $\tilde{\tau}$ and $m > 1$, the set $L_{\pi}^m(0, \tilde{\tau})$ contains all processes $\psi \in G_{\text{loc}}(\mu)$ such that

$$\mathbb{E} \left[\int_0^{\tilde{\tau}} \int_{\mathcal{Z}} |\psi_s(z)|^m \mu(dz) ds \right] < +\infty.$$

By $L_{\mu}^m = L^m(\mathcal{Z}, \mu; \mathbb{R}^d)$ we denote the set of measurable functions $\psi : \mathcal{Z} \rightarrow \mathbb{R}^d$ such that

$$\|\psi\|_{L_{\mu}^m}^m = \int_{\mathcal{Z}} |\psi(z)|^m \mu(dz) < +\infty.$$

By \mathcal{M}^{\perp} we denote the set of càdlàg local martingales orthogonal to $\tilde{\pi}$. If $M \in \mathcal{M}^{\perp}$ then $\mathbb{E}(\Delta M * \pi | \tilde{\mathcal{P}}) = 0$, where the product $*$ denotes the integral process (see II.1.5 in [17]). For any stopping time $\tilde{\tau}$ the set $\mathcal{M}^m(0, \tilde{\tau})$ is the subset of all martingales such that $\mathbb{E}([M]_{\tilde{\tau}}^{m/2}) < +\infty$. Finally, for $m > 1$, $\mathbb{S}^m(0, \tilde{\tau})$ is the set of all progressively measurable càdlàg processes F such that $\mathbb{E}[\sup_{t \in [0, \tilde{\tau}]} |F_t|^m] < +\infty$. The set $\mathbb{H}^m(0, \tilde{\tau})$ contains all progressively measurable càdlàg processes F such that $\mathbb{E} \left[\left(\int_0^{\tilde{\tau}} |F_t|^2 dt \right)^{m/2} \right] < +\infty$.

1.2. Deterministic terminal times

In this section let $T > 0$ and let ξ be a \mathcal{F}_T -measurable random variable. We denote by \mathcal{S} the set $\{\xi = +\infty\}$. Since we explicitly allow ξ to take the value $+\infty$ with positive probability, we need to specify a weak notion of solutions to (1). We relax the usual definition of a solution to a BSDE by only requiring that (1) holds strictly before time T .

Definition 1 (*Weak Supersolution in the Case of Deterministic Terminal Times*). We say that a triple of processes (Y, ψ, M) is a supersolution to the BSDE (1) with singular terminal condition $Y_T = \xi$ if it satisfies:

1. $M \in \mathcal{M}^{\perp}$, $\psi \in G_{\text{loc}}(\pi)$ and there exists some $\ell > 1$ such that for all $t < T$:

$$\mathbb{E} \left(\sup_{s \in [0, t]} |Y_s|^{\ell} + \int_0^t \int_{\mathcal{Z}} |\psi_s(z)|^{\ell} \mu(dz) ds + [M]_t^{\ell/2} \right) < +\infty;$$

2. Y is bounded from below by a process $\bar{Y} \in \mathbb{S}^2(0, T)$;
3. for all $0 \leq s \leq t < T$:

$$Y_s = Y_t + \int_s^t f(u, Y_u, \psi_u) du - \int_s^t \int_{\mathcal{Z}} \psi_u(z) \tilde{\pi}(dz, du) - \int_s^t dM_u.$$

4. $\liminf_{t \rightarrow T} Y_s \geq \xi$ a.s.

We say that (Y, ψ, M) is a minimal supersolution to the BSDE (1) if for any other supersolution (Y', ψ', M') we have $Y_t \leq Y'_t$ a.s. for any $t \in [0, T)$.

To establish existence of a minimal supersolution to BSDE (1) we impose the following conditions on the driver $f : \Omega \times [0, T] \times \mathbb{R} \times \mathbb{R}^d \rightarrow \mathbb{R}$. For notational convenience we write $f_t^0 = f(t, 0, 0)$.

A1. The function $y \mapsto f(t, y, \psi)$ is continuous and monotone: there exists $\chi \in \mathbb{R}$ such that a.s. and for any $t \in [0, T]$ and $\psi \in L_\mu^2$

$$(f(t, y, \psi) - f(t, y', \psi))(y - y') \leq \chi(y - y')^2.$$

A2. There exists a progressively measurable process $\kappa = \kappa^{y, \psi, \phi} : \Omega \times \mathbb{R}_+ \times \mathcal{Z} \rightarrow \mathbb{R}$ such that

$$f(t, y, \psi) - f(t, y, \phi) \leq \int_{\mathcal{Z}} (\psi(z) - \phi(z)) \kappa_t^{y, \psi, \phi}(z) \mu(dz)$$

with $\mathbb{P} \otimes \text{Leb} \otimes \mu$ -a.e. for any (y, ψ, ϕ) , $-1 \leq \kappa_t^{y, \psi, \phi}(z)$ and $|\kappa_t^{y, \psi, \phi}(z)| \leq \vartheta(z)$ where $\vartheta \in L_\mu^2$.

A3. For every $n > 0$ it holds that $\sup_{|y| \leq n} |f(t, y, 0) - f_t^0| \in L^1((0, T) \times \Omega)$.

A4. The negative parts of ξ and f^0 are square integrable: $\xi^- \in L^2(\Omega)$ and $(f^0)^- \in L^2((0, T) \times \Omega)$.

Conditions A1–A4 will ensure existence and uniqueness of the solution for a version of BSDE (1), where the terminal condition ξ is replaced by $\xi \wedge L$ and the generator f by f^L (see (6)) for some $L > 0$. We obtain the minimal supersolution with singular terminal condition ξ by letting L tend to ∞ . To ensure that in the limit $L \rightarrow \infty$ the solution component Y attains the value ∞ on \mathcal{S} at time T but is finite before time T , we have to impose some further growth behavior on f . We assume that f decreases at least polynomially in the y -variable.

A5. There exists a constant $q > 1$ and a positive process η such that for any $y \geq 0$

$$f(t, y, \psi) \leq -\frac{p-1}{\eta_t^{q-1}} |y|^q + f(t, 0, \psi).$$

p is the Hölder conjugate of q .

A6. There exists $\ell > 1$ such that $\mathbb{E} \int_0^T [\eta_s + (T-s)^p (f_s^0)^+]^\ell ds < +\infty$.

A7. There exists $k > \max(\frac{\ell}{\ell-1}, 2)$ such that $\int_{\mathcal{Z}} |\vartheta(z)|^k \mu(dz) < +\infty$.

Assumptions (A). We say that Assumptions (A) are satisfied if all seven hypotheses A1–A7 hold. \diamond

Remark 1 (On A1). We can suppose w.l.o.g. that $\chi = 0$. Indeed if (Y, ψ, M) is a solution of (1) then $(\bar{Y}, \bar{\psi}, \bar{M})$ with

$$\bar{Y}_t = e^{\chi t} Y_t, \quad \bar{\psi}_t = e^{\chi t} \psi_t, \quad d\bar{M}_t = e^{\chi t} dM_t$$

satisfies an analogous BSDE with terminal condition $\bar{\xi} = e^{\chi T} \xi$, and generator

$$\bar{f}(t, y, \psi) = [e^{\chi t} f(t, e^{-\chi t} y, e^{-\chi t} \psi) - \chi y]$$

and \bar{f} satisfies the same assumptions with $\chi = 0$. In the rest of this section, we will suppose that $\chi = 0$.

Remark 2 (On A2). The second condition A2 implies that f is Lipschitz continuous w.r.t. ψ uniformly in ω, t and y . Indeed by Cauchy–Schwarz's inequality

$$f(t, y, \psi) - f(t, y, \phi) \leq \left| \int_{\mathcal{Z}} (\psi(z) - \phi(z)) \kappa_t^{y, \psi, \phi}(z) \mu(dz) \right| \leq \|\vartheta\|_{L_\mu^2} \|\psi - \phi\|_{L_\mu^2}.$$

And conversely since

$$f(t, y, \phi) - f(t, y, \psi) \leq \int_{\mathcal{Z}} (\phi(z) - \psi(z)) \kappa_t^{y, \phi, \psi}(z) \mu(dz),$$

we obtain

$$f(t, y, \psi) - f(t, y, \phi) \leq \|\vartheta\|_{L_\mu^2} \|\psi - \phi\|_{L_\mu^2}.$$

Remark 3 (On A5). It follows from Condition A3 and A5 that the process $1/\eta^{q-1}$ must be in $L^1((0, T) \times \Omega)$

$$\mathbb{E} \int_0^T \frac{1}{\eta_t^{q-1}} dt < +\infty. \quad (4)$$

Let us just mention that it is possible to assume only integrability w.r.t. t a.s. in A2 (see [5, Remark 4.3]).

In this section, our main result can be summarized as follows.

Theorem 1. Under Assumptions (A) there exists a minimal supersolution (Y, ψ, M) to (1) with singular terminal condition $Y_T = \xi$.

To prove Theorem 1 we proceed as in [3] by truncation. The complete statement and the proof of this result is divided into Propositions 1–4. For any $L \geq 0$ we consider the BSDE

$$dY_t^L = -f^L(t, Y_t^L, \psi_t^L)dt + \int_{\mathcal{Z}} \psi_t^L(z) \tilde{\pi}(dz, dt) + dM_t^L \quad (5)$$

with bounded terminal condition $Y_T^L = \xi \wedge L$ and where

$$f^L(t, y, \psi) = (f(t, y, \psi) - f_t^0) + f_t^0 \wedge L. \quad (6)$$

Proposition 1. Under Assumptions (A), there exists for every $L > 0$ a unique solution (Y^L, ψ^L, M^L) to (5) with $Y^L \in \mathbb{S}^2(0, T)$, $\psi^L \in L_\pi^2(0, T)$, $M^L \in \mathcal{M}^2(0, T) \cap \mathcal{M}^\perp$. Moreover there exists a process \bar{Y} in $\mathbb{S}^2(0, T)$, independent of L , such that a.s. for any $t \in [0, T]$, $\bar{Y}_t \leq Y_t^L$. If $(f_t^0)^- = \xi^- = 0$, then $\bar{Y}_t = 0$, and Y_t^L is non negative.

Proof. From assumptions A1, A2 and A4, it follows that f^L is monotone w.r.t. y , Lipschitz continuous w.r.t. ψ , and $f^L(t, 0, 0) = f_t^0 \wedge L \in L^2((0, T) \times \Omega)$. Moreover for every $n > 0$ and $|y| \leq n$:

$$|f^L(t, y, 0) - f^L(t, 0, 0)| = |f(t, y, 0) - f_t^0| \leq \sup_{|y| \leq n} |f(t, y, 0) - f_t^0|.$$

By Assumption A3, the mapping $t \mapsto \sup_{|y| \leq n} |f(t, y, 0) - f_t^0|$ is in $L^1((0, T) \times \Omega)$. From Theorem 1 in [23] it follows that there exists a unique solution (Y^L, ψ^L, M^L) to (5) with terminal condition $\xi \wedge L$. This solution satisfies

$$\mathbb{E} \left[\sup_{0 \leq t \leq T} |Y_t^L|^2 + \int_0^T \int_{\mathcal{Z}} (\psi_t^L(z))^2 \mu(dz) dt + [M^L]_T \right] < +\infty.$$

Next, we construct the lower bound \bar{Y} . Let us take $\zeta = -\xi^-$ and $g(t, y, \psi) = (f(t, y, \psi) - f_t^0) - (f_t^0)^-$. The solution $(\bar{Y}, \bar{\psi}, \bar{M})$ with $\bar{Y} \in \mathbb{S}^2(0, T)$ of the BSDE with data (ζ, g) does not depend on L , and by comparison (Proposition 4 in [23]) we have $\bar{Y}_t \leq Y_t^L$ a.s. for any $t \in [0, T]$. \square

Next, we derive an upper bound for the family Y^L which is independent of L .

Proposition 2. *For every $t \in [0, T]$ the random variable Y_t^L is bounded from above by $L(1 + T)$ and for $t \in [0, T)$ the following estimate holds:*

$$Y_t^L \leq \frac{K_\vartheta}{(T-t)^p} \left[\mathbb{E} \left(\int_t^T \left(\eta_s + (T-s)^p (f_s^0)^+ \right)^\ell ds \middle| \mathcal{F}_t \right) \right]^{1/\ell} \quad (7)$$

where K_ϑ is a constant depending only on ϑ .

Proof. Let us first consider the triple $(A_t, B_t, C_t) = (L(1 + (T-t)), 0, 0)$. It is the solution of the BSDE with terminal condition L and constant generator equal to L . By assumption A1, f is monotone and hence it holds that $f(t, A_t, B_t) \leq f_t^0$. Thus by the definition (6) of f^L we have $f^L(t, A_t, B_t) \leq L$. By the comparison principle (Proposition 4 in [23]) we obtain $Y_t^L \leq A_t \leq L(T+1)$ a.s. for any $t \in [0, T]$.

This upper bound depends on L . Next, we verify (7). We consider the driver

$$h(t, y, \psi) = b_t^L - p \frac{1}{T-t} y + f(t, 0, \psi)$$

with $b_t^L = \frac{\eta_t}{(T-t)^p} + ((f_t^0)^+ \wedge L)$. Let $\varepsilon > 0$ and denote by $(\mathcal{Y}^{\varepsilon, L}, \phi^{\varepsilon, L}, N^{\varepsilon, L})$ the solution process of the BSDE on $[0, T - \varepsilon]$ with driver h and terminal condition $\mathcal{Y}_{T-\varepsilon}^{\varepsilon, L} = Y_{T-\varepsilon}^{L,+} \geq 0$. Recall that

$$f(t, 0, \psi) \leq \int_{\mathcal{Z}} \psi(z) \kappa_t^{0, \psi, 0}(z) \mu(dz).$$

Hence by a comparison argument with the solution for linear BSDE (see [30, Lemma 4.1]) we have

$$\mathcal{Y}_t^{\varepsilon, L} \leq \mathbb{E} \left[\Gamma_{t, T-\varepsilon} Y_{T-\varepsilon}^{L,+} + \int_t^{T-\varepsilon} \Gamma_{t,s} b_s^L ds \middle| \mathcal{F}_t \right]$$

where for $t \leq s \leq T - \varepsilon$

$$\Gamma_{t,s} = \exp \left(- \int_t^s \frac{p}{T-u} du \right) V_{t,s}^{\varepsilon, L} = \left(\frac{T-s}{T-t} \right)^p V_{t,s}^{\varepsilon, L}$$

and

$$V_{t,s}^{\varepsilon, L} = 1 + \int_t^s \int_{\mathcal{Z}} V_{t,u}^{\varepsilon, L} \kappa_u^{0, \phi^{\varepsilon, L}, 0}(z) \tilde{\pi}(dz, du). \quad (8)$$

Hence

$$\mathcal{Y}_t^{\varepsilon, L} \leq \frac{1}{(T-t)^p} \mathbb{E} \left[\varepsilon^p V_{t, T-\varepsilon}^{\varepsilon, L} Y_{T-\varepsilon}^{L,+} + \int_t^{T-\varepsilon} V_{t,s}^{\varepsilon, L} (T-s)^p b_s^L ds \middle| \mathcal{F}_t \right].$$

Since $b^L \geq 0$ it holds that $\mathcal{Y}_t^{\varepsilon, L} \geq 0$ a.s. for every $t \in [0, T]$. Hence from Condition A5

$$f^L(t, \mathcal{Y}_t^{\varepsilon, L}, \phi_t^{\varepsilon, L}) \leq -\frac{p-1}{\eta_t^{q-1}} (\mathcal{Y}_t^{\varepsilon, L})^q + f^L(t, 0, \phi_t^{\varepsilon, L}).$$

It follows that

$$\begin{aligned} f^L(t, \mathcal{Y}_t^{\varepsilon, L}, \phi_t^{\varepsilon, L}) &\leq h(t, \mathcal{Y}_t^{\varepsilon, L}, \phi_t^{\varepsilon, L}) - \frac{p-1}{\eta_t^{q-1}} (\mathcal{Y}_t^{\varepsilon, L})^q - \frac{a_t^{p-1}}{(T-t)^p} + \frac{p}{T-t} \mathcal{Y}_t^{\varepsilon, L} \\ &\leq h(t, \mathcal{Y}_t^{\varepsilon, L}, \phi_t^{\varepsilon, L}), \end{aligned}$$

where we used the Young inequality: $c^p + (p-1)y^q - pcy \geq 0$ which holds for all $c, y \geq 0$. The comparison theorem implies $Y_t^L \leq \mathcal{Y}_t^{\varepsilon, L}$ for all $t \in [0, T-\varepsilon]$ and $\varepsilon > 0$.

Recall once again from Condition A7 that $V_{t,\cdot}^{\varepsilon, L}$ belongs to $\mathbb{H}^k(0, T-\varepsilon)$ for $k \geq 2$. From the upper bound $Y_t^L \leq A_t \leq L(T+1)$ and from the integrability property of $V_{t,\cdot}^{\varepsilon, L}$, with dominated convergence, by letting $\varepsilon \downarrow 0$ we obtain a.s.

$$\mathbb{E} \left[\varepsilon^p V_{t, T-\varepsilon}^{\varepsilon, L} Y_{T-\varepsilon}^{L,+} \middle| \mathcal{F}_t \right] \rightarrow 0.$$

From Assumption A7 and by the proof of Proposition A.1 in [30], there exists a constant K_ϑ such that a.s.

$$\mathbb{E} \left[\int_t^{T-\varepsilon} (V_{t,s}^{\varepsilon, L})^k ds \middle| \mathcal{F}_t \right] \leq K_\vartheta.$$

From Assumption A6, it follows that the process $((T-t)^p b_t^L, 0 \leq t \leq T)$ belongs to $\mathbb{H}^\ell(0, T)$. Therefore by Hölder inequality we obtain

$$\mathbb{E} \left[\int_t^{T-\varepsilon} V_{t,s}^{\varepsilon, L} (T-s)^p b_s^L ds \middle| \mathcal{F}_t \right] \leq K_\vartheta \mathbb{E} \left[\int_t^T ((T-s)^p b_s^L)^\ell ds \middle| \mathcal{F}_t \right]^{1/\ell}.$$

Hence we can pass to the limit as $\varepsilon \downarrow 0$

$$Y_t^L \leq \frac{K_\vartheta}{(T-t)^p} \mathbb{E} \left[\int_t^T ((T-s)^p b_s^L)^\ell ds \middle| \mathcal{F}_t \right]^{1/\ell}.$$

Assumption A6 implies by monotone convergence for $L \rightarrow \infty$

$$Y_t^L \leq \frac{K_\vartheta}{(T-t)^p} \mathbb{E} \left[\int_t^T \left(\eta_s + (T-s)^p (f_s^0)^+ \right)^\ell ds \middle| \mathcal{F}_t \right]^{1/\ell} < +\infty.$$

Thus we obtain the upper bound in (7). \square

The constants K_ϑ and $\ell > 1$ in (7) come from the growth condition on f w.r.t. ψ and from the lack of an estimate of ψ^L independent of L . If we assume that $f(t, 0, \psi)$ is bounded, then we can obtain a simpler estimate.

Lemma 1. *If there exists a non negative process K_t^f such that a.s. for any t and ψ ,*

$$f(t, 0, \psi) \leq K_t^f, \quad \text{with } \mathbb{E} \int_0^T (T-s)^p K_s^f ds < +\infty \quad (9)$$

then

$$Y_t^L \leq \frac{1}{(T-t)^p} \mathbb{E} \left[\int_t^T \left(\eta_s + 2(T-s)^p K_s^f \right) ds \middle| \mathcal{F}_t \right]. \quad (10)$$

Proof. The proof is almost the same as for [Proposition 2](#). Therefore, we only outline the main modification. Note that (9) implies that $f_t^0 \leq K_t^f$ a.s. We consider the generator h given by

$$h(t, y, \psi) = h(t, y) = \frac{\eta_t}{(T-t)^p} + 2K_t^f - p \frac{1}{T-t} y = b_t - p \frac{1}{T-t} y.$$

Since h is linear and does not depend on ψ , we have:

$$\mathcal{Y}_t^{\varepsilon, L} = \frac{1}{(T-t)^p} \mathbb{E} \left[\varepsilon^p Y_{T-\varepsilon}^{L,+} + \int_t^{T-\varepsilon} (T-s)^p b_s ds \middle| \mathcal{F}_t \right].$$

Hence we can pass to the limit when ε goes to zero and we obtain

$$Y_t^L \leq \frac{1}{(T-t)^p} \mathbb{E} \left[\int_t^T (T-s)^p b_s ds \middle| \mathcal{F}_t \right]$$

which is Inequality (10). \square

Next, we show that by passing to the limit $L \rightarrow \infty$ we obtain a supersolution of (1) with singular terminal condition ξ .

Proposition 3. Assume that Assumptions (A) hold. Let (Y^L, ψ^L, M^L) be the solution of BSDE (5) obtained in [Proposition 1](#). Then there exists a process (Y, ψ, M) such that for every $0 \leq t < T$, Y^L converges to Y in $\mathbb{S}^\ell(0, t)$, ψ^L converges in $L_\pi^\ell([0, t])$ to ψ and M^L converges in $\mathcal{M}^\ell(0, t)$ to M . The limit process (Y, ψ, M) is a weak supersolution for the BSDE (1) with singular terminal condition ξ . Moreover Y satisfies the estimate (7)

$$Y_t \leq \frac{K_\vartheta}{(T-t)^p} \mathbb{E} \left[\int_t^T \left[\eta_s + (T-s)^p (f_s^0)^+ \right]^\ell ds \middle| \mathcal{F}_t \right]^{1/\ell}.$$

Proof. The comparison result (see Proposition 4 in [23]) yields that $Y^L \leq Y^N$ if $N > L$. Hence, for all $t \leq T$ we can define Y_t as the increasing limit of Y_t^L as $L \rightarrow \infty$. Recall that by [Proposition 1](#), Y^L is bounded from below uniformly in L by some process $\bar{Y} \in \mathbb{S}^2(0, T)$. Thus Y is also bounded from below by \bar{Y} .

By Eq. (7) for fixed $t < T$ the family of random variables $(Y_t^L, L \geq 0)$ is bounded from above:

$$Y_t^{L,+} \leq \frac{K_\vartheta}{(T-t)^p} \mathbb{E} \left[\int_t^T \left[\eta_s + (T-s)^p (f_s^0)^+ \right]^\ell ds \middle| \mathcal{F}_t \right]^{1/\ell}.$$

Once again by Assumption A6, the random variable on the right hand side of the inequality above is in $L^\ell(\Omega)$. By dominated convergence, Y_t^L converges to Y_t in $L^\ell(\Omega)$ for $t < T$.

For the convergence of (ψ^L, M^L) let $0 \leq s \leq t < T$. For L and N non negative, we put

$$\widehat{Y}_s = Y_s^N - Y_s^L, \quad \widehat{\psi}_s(z) = \psi_s^N(z) - \psi_s^L(z), \quad \widehat{M}_s = M_s^N - M_s^L.$$

Let us define $a = \ell \|\vartheta\|_{L_\mu^2}^2 / (\ell - 1)$. By [Lemma 9](#) in the [Appendix](#) there exists a constant K_ℓ depending only on ℓ such that

$$\begin{aligned} & \mathbb{E} \left[\sup_{s \in [0, t]} e^{as} |\widehat{Y}_s|^\ell + \left(\int_0^t e^{2au/\ell} \int_{\mathcal{Z}} |\widehat{\psi}_u(z)|^2 \mu(dz) du \right)^{\ell/2} + \left(\int_0^t e^{2au/\ell} d[\widehat{M}]_u \right)^{\ell/2} \right] \\ & \leq K_\ell \mathbb{E} \left(e^{at} |\widehat{Y}_t|^\ell + \int_0^t e^{au} |f_u^0 \wedge N - f_u^0 \wedge L|^\ell du \right). \end{aligned}$$

Since $f^0 \in \mathbb{H}^\ell(0, t)$ (see condition A6), the right-hand side converges to zero as N and L go to $+\infty$. Then (ψ^L) is a Cauchy sequence in $L^\ell_\pi(0, t)$ and converges to $\psi \in L^\ell_\pi(0, t)$ for every $t < T$. The same holds for the sequence (M^L) in $\mathcal{M}^\ell(0, t)$. Moreover the previous inequality yields that $\mathbb{E}(\sup_{0 \leq s \leq t} |Y_s|^\ell) < +\infty$.

Finally, taking the limit as L goes to ∞ in (5) implies that (Y, ψ, M) satisfies (1) for every $0 \leq s \leq t < T$. From the structure of the BSDE, we deduce that Y is càdlàg on $[0, T)$. In other words $Y \in \mathbb{S}^\ell(0, T - \varepsilon)$ for any $\varepsilon > 0$.

Since the filtration is quasi-left continuous, we have: $\lim_{t \nearrow T} Y_t^L = \xi \wedge L$. Indeed, in Eq. (5), using Fubini's theorem for conditional expectation, the only discontinuous term could be the martingale term M^L . But the assumption on the filtration shows that M^L has no jump at time T (see [20, Proposition 25.19]). Now for any $L \geq 0$ we have

$$\liminf_{t \uparrow T} Y_t \geq \liminf_{t \uparrow T} Y_t^L = \xi \wedge L,$$

which gives the desired inequality $\liminf_{t \nearrow T} Y_t \geq \xi$. In particular, $(\liminf_{t \nearrow T} Y_t) \mathbf{1}_S = +\infty$. This achieves the proof of the theorem. \square

Remark 4. Under Condition (9), the estimate (10) is then also an upper bound for Y .

To finish the proof of Theorem 1 let us prove the minimality of the limit process.

Proposition 4. The solution obtained in Proposition 3 is minimal. If (Y', ψ', M') is another weak supersolution of (1) with terminal condition ξ , then $Y'_t \geq Y_t$ a.s. for all $t \in [0, T]$.

Proof. Fix $L > 0$ and let (Y^L, ψ^L, M^L) denote the solution of (5) with terminal condition $Y_T^L = \xi \wedge L$. Let (Y', ψ', M') be a weak supersolution of (1) in the sense of Definition 1. Set

$$\widehat{Y}_s = Y'_s - Y_s^L, \quad \widehat{\psi}_s(z) = \psi'_s(z) - \psi_s^L(z), \quad \widehat{M}_s = M'_s - M_s^L.$$

We have

$$f(t, Y'_t, \psi'_t) - f(t, Y_t^L, \psi_t^L) = -c_t \widehat{Y}_t + (f(t, Y_t^L, \psi'_t) - f(t, Y_t^L, \psi_t^L))$$

with

$$-c_t = \frac{f(t, Y'_t, \psi'_t) - f(t, Y_t^L, \psi'_t)}{\widehat{Y}_t} \mathbf{1}_{\widehat{Y}_t \neq 0}.$$

Note that from condition A1, $-c_t \leq \chi = 0$. For every $t < T$ the process $(\widehat{Y}, \widehat{\psi}, \widehat{M})$ solves the BSDE

$$d\widehat{Y}_s = \left[c_s \widehat{Y}_s - (f_s^0 - L)^+ - (f(s, Y_s^L, \psi'_s) - f(s, Y_s^L, \psi_s^L)) \right] ds + \int_{\mathcal{Z}} \widehat{\psi}_s(z) \widetilde{\pi}(dz, ds) + d\widehat{M}_s$$

on $[0, t]$ with terminal condition $\widehat{Y}_t = Y'_t - Y_t^L$. Moreover from A2 it holds that

$$f(s, Y_s^L, \psi'_s) - f(s, Y_s^L, \psi_s^L) \geq \int_{\mathcal{Z}} \kappa_s^{Y_s^L, \psi_s^L, \psi'_s} \widehat{\psi}_s(z) \mu(dz).$$

From Lemma 10 in [23] and Lemma 4.1 in [30], we have

$$\widehat{Y}_s \geq \mathbb{E} \left[\widehat{Y}_t \Gamma_{s,t} + \int_s^t \Gamma_{s,u} (f_u^0 - L)^+ du \middle| \mathcal{F}_s \right]$$

where $\Gamma_{s,t} = \exp\left(-\int_s^t c_u du\right) \zeta_{s,t}$ with $\zeta_{s,s} = 1$ and

$$d\zeta_{s,t} = \zeta_{s,t} \int_{\mathcal{Z}} \kappa_t^{Y_t^L, \psi^L, \psi'} \tilde{\pi}(dz, dt).$$

Our assumptions ensure that ζ is non negative and belongs to $\mathbb{H}^k(0, T)$. From [Proposition 2](#) we have $Y_t^L \leq (1+T)L$ and hence $\hat{Y}_t \geq -((Y_t')^- + (1+T)L)$. Thus $\hat{Y}_{\Gamma_{s,\cdot}}$ is bounded from below by a process in $\mathbb{S}^m(0, T)$ for some $m > 1$. We can apply Fatou's lemma to obtain

$$\hat{Y}_s = \liminf_{t \nearrow T} \mathbb{E} \left[\hat{Y}_t \Gamma_{s,t} + \int_s^t \Gamma_{s,u} (f_u^0 - L)^+ du \middle| \mathcal{F}_s \right] \geq \mathbb{E} \left[\liminf_{t \nearrow T} (\hat{Y}_t \Gamma_{s,t}) \middle| \mathcal{F}_s \right].$$

The process $(\Gamma_{s,t}, s \leq t \leq T)$ is càdlàg and non negative. Hence a.s.

$$\liminf_{t \nearrow T} (\hat{Y}_t \Gamma_{s,t}) = (\liminf_{t \nearrow T} \hat{Y}_t) \Gamma_{s,T^-} \geq (\xi - \xi \wedge L) \Gamma_{s,T^-} \geq 0.$$

Finally, $Y_s' \geq Y_s^L$ for any $s \in [0, T]$ and $L \geq 0$. Taking the limit as L goes to ∞ yields the claim. \square

Remark 5. Note that all these results can be extended immediately if we assume that the filtration supports also a Brownian motion W and if our singular BSDE has form

$$dY_t = f(t, Y_t, Z_t, \psi_t) dt + Z_t dW_t + \int_{\mathcal{Z}} \psi_t(z) \tilde{\pi}(dz, dt) + dM_t,$$

where f satisfies conditions (A) and is supposed to be Lipschitz continuous in z .

1.3. Random terminal times

In this section we consider the case where the terminal time τ is random. Again we proceed via truncation of the terminal condition to obtain a family of solutions $(Y^L)_{L>0}$ to [\(5\)](#) with bounded terminal condition $Y_\tau^L = \xi \wedge L$.

Assumptions A1, A2 and A5 from [Section 1.2](#) remain in force, while assumptions A2, A4 and A6 are strengthened. The condition A7 was used to construct the a priori estimate [\(7\)](#) and is unnecessary here. Moreover, we need an extra condition between the random time τ and the growth coefficients χ in A1 and K in A2 of f . This condition is denoted by B. Next, we present the complete list of assumptions.

A1. The function $y \mapsto f(t, y, \psi)$ is continuous and monotone: there exists $\chi \in \mathbb{R}$ such that a.s. and for any $t \in [0, \infty)$ and $\psi \in L_\mu^2$

$$(f(t, y, \psi) - f(t, y', \psi))(y - y') \leq \chi(y - y')^2.$$

A2. There exists a progressively measurable process $\kappa = \kappa^{y, \psi, \phi} : \Omega \times \mathbb{R}_+ \times \mathcal{Z} \rightarrow \mathbb{R}$ such that

$$f(t, y, \psi) - f(t, y, \phi) \leq \int_{\mathcal{Z}} (\psi(z) - \phi(z)) \kappa_t^{y, \psi, \phi}(z) \mu(dz)$$

with $\mathbb{P} \otimes \text{Leb} \otimes \mu$ -a.e. for any (y, ψ, ϕ) , $-1 \leq \kappa_t^{y, \psi, \phi}(z)$ and $|\kappa_t^{y, \psi, \phi}(z)| \leq \vartheta(z)$ where $\vartheta \in L_\mu^2$. As in [Section 1.2](#) we denote by $K = \|\vartheta\|_{L_\mu^2}$ is the Lipschitz constant of f w.r.t. ψ (cf. [Remark 2](#)).

Let δ^* denote the value

$$\delta^* = \begin{cases} -\infty & \text{if } 2\chi < K^2, \\ K^2 + 2\chi & \text{if } 2|\chi| \leq K^2, \\ \chi \left(1 + \frac{K}{\sqrt{2\chi}}\right)^2 & \text{if } 2\chi > K^2. \end{cases} \quad (11)$$

B. There exists $\rho > \delta^*$ such that

$$\mathbb{E}(e^{\rho\tau}) < +\infty.$$

If Condition B holds, then we put

$$h^* = \begin{cases} 0 & \text{if } 2\chi < -K^2, \\ \frac{2\rho}{\rho - \delta^* + (\sqrt{\rho} - K\sqrt{2})^2 \mathbf{1}_{\rho > 2K^2}} & \text{if } 2|\chi| \leq K^2, \\ \frac{\rho}{\sqrt{\rho} + \sqrt{\chi} - \frac{K}{\sqrt{2}}} \times \frac{1}{\sqrt{\rho} - \sqrt{\delta^*}} & \text{if } 2\chi > K^2. \end{cases} \quad (12)$$

A3'. For every $j > 0$ and $n \geq 0$, the process $U_t(j) = \sup_{|y| \leq j} |f(t, y, 0) - f_t^0|$ is in $L^1((0, n) \times \Omega)$ and there exists $m > h^*$ such that $\mathbb{E} \int_0^\tau |U_t(j)|^m dt < +\infty$.

A4'. ξ^- and $(f^0)^-$ are bounded.

A5. There exists a constant $q > 1$ and a positive process η such that for any $y \geq 0$

$$f(t, y, \psi) \leq -\frac{p-1}{\eta_t^{q-1}} |y|^q + f(t, 0, \psi).$$

p is the Hölder conjugate of q .

A6'. η and f^0 are bounded.

Note that Hypotheses A3' and A5 imply that

$$\mathbb{E} \int_0^\tau \frac{1}{\eta_s^{(q-1)m}} ds < +\infty. \quad (13)$$

Remark 6 (On A1). For a random terminal time, we cannot assume w.l.o.g. that $\chi = 0$ in A1.

Remark 7 (On B and A3'). If $2\chi < -K^2$, Condition B is satisfied for any stopping time τ (including $\tau = +\infty$ a.s.) since one can choose $\rho < 0$ in this case.

Note that δ^* and h^* are non decreasing functions of χ and h^* is a non increasing function of ρ , with $\lim_{\rho \rightarrow \delta^*} h^* = +\infty$ and $\lim_{\rho \rightarrow +\infty} h^* = 1$.

Assumptions (A'). We say that Conditions (A') are satisfied if all following hypotheses hold: A1, A2, A3', A4', A5, A6' and B. \diamond

Under the above conditions, Proposition 5 shows that the truncated BSDE (5) has a unique solution (Y^L, ψ^L, M^L) . The crucial difference in order to obtain a supersolution to the BSDE with singular terminal condition to the case of a deterministic terminal time, is the derivation of a uniform upper bound for the family of processes (Y^L) (cf. Inequality (7)). Example 1 shows that in general such an upper bound does not exist and that there exist stopping times τ such that

the sequence (Y_t^L) converges to ∞ as $L \rightarrow \infty$ for $t < \tau$. Consequently one has to restrict the class of terminal times. Here we draw inspiration from [29], where BSDEs with random terminal time and singular terminal condition have been studied for the first time, and consider the case where τ is given by a first exit time $\tau = \tau_D$ of a diffusion Ξ from a set D .

More precisely, we assume that the filtration \mathbb{F} supports a d -dimensional Brownian motion W which is orthogonal to π and we introduce a forward process Ξ in \mathbb{R}^d , that is a solution to the stochastic differential equation

$$d\Xi_t = b(\Xi_t)dt + \sigma(\Xi_t)dW_t \quad (14)$$

with some initial value $\Xi_0 \in \mathbb{R}^d$. The functions $b : \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $\sigma : \mathbb{R}^d \rightarrow \mathbb{R}^d \times \mathbb{R}^d$ satisfy a global Lipschitz condition: there exists some $K > 0$ such that

$$\forall x, y \in \mathbb{R}^d \quad \|\sigma(x) - \sigma(y)\| + \|b(x) - b(y)\| \leq K\|x - y\|.$$

Under this assumption there exists a unique strong solution Ξ to (14). Let D be an open bounded subset of \mathbb{R}^d , whose boundary is at least of class C^2 (see for example [11, Section 6.2], for the definition of a regular boundary). From now on Ξ_0 is fixed and supposed to be in D . We define the stopping time τ as the first exit time of D , i.e.

$$\tau = \tau_D = \inf\{t \geq 0, \Xi_t \notin D\}. \quad (15)$$

The condition B imposes some implicit hypotheses between the generator f , the set D and the coefficients of the SDE (14). In the next lemma, we give sufficient conditions to ensure B. Let us denote by R the diameter of D :

$$R = \sup\{|x - y|, (x, y) \in D^2\},$$

by $\|\sigma\|$ the spectral norm of σ

$$\|\sigma\| = \sup_{x \in \mathbb{R}^d} \sup_{v \in \mathbb{R}^d, |v| \leq 1} v \cdot (\sigma(x)\sigma^*(x))v,$$

and by $\|b\|$ the sup norm of b :

$$\|b\| = \sup_{x \in \mathbb{R}^d} |b(x)|.$$

Define j_d to be equal to $\pi^2/4$ if $d = 1$ and to be equal to the first positive zero of the Bessel function of first kind $J_{d/2-1}$ if $d \geq 2$ (for $d = 2$, $j_2 \approx 2.4048$).

Lemma 2. 1. Assume that there exists $\nu > 0$ and $v \in \mathbb{R}^d$ such that for all $x \in \mathbb{R}^d$ it holds that $b(x) \cdot v \geq \nu > 0$. If $\delta^* < \frac{\nu^2}{\|\sigma\|}$, then Condition B holds for all $\rho \in (\delta^*, \frac{\nu^2}{\|\sigma\|})$.
 2. Assume that $b = 0$ (there is no drift) and $\sigma\sigma^*$ is uniformly elliptic, that is there exists a constant $\alpha > 0$ such that $(\sigma\sigma^*)(x) \geq \alpha \text{Id}$ for all $x \in \mathbb{R}^d$. If $\delta^* < \frac{2\alpha}{R^2}(j_d)^2$, then Condition B holds for all $\rho \in (\delta^*, \frac{2\alpha}{R^2}(j_d)^2)$.

Proof. Since D is bounded and not equal to a singleton it holds that $0 < R < +\infty$.

Assume first that there exists $\nu > 0$ and $v \in \mathbb{R}^d$ such that for all $x \in \mathbb{R}^d$, the scalar product between $b(x)$ and v is bounded from below by ν . W.l.o.g. we can assume that $|v| = 1$. Let $t > R/\nu$. On the set $\{\tau > t\}$, it holds that Ξ_0 and Ξ_s are in D . This implies on the set $\{\tau > t\}$,

for any $0 \leq s \leq t$, that

$$\sup_{0 \leq s \leq t} (-v) \cdot \left(\Xi_s - \Xi_0 - \int_0^s b(\Xi_u) du \right) \geq tv - R.$$

Hence from Theorem II.2.2 in [27]

$$\begin{aligned} \mathbb{P}(\tau > t) &\leq \mathbb{P} \left(\sup_{0 \leq s \leq t} (-v) \cdot \left(\Xi_s - \Xi_0 - \int_0^s b(\Xi_u) du \right) \geq tv - R \right) \\ &\leq \exp \left(-\frac{(tv - R)^2}{\|\sigma\|t} \right). \end{aligned}$$

This implies for all $t > R/v$ that

$$e^{\rho t} \mathbb{P}(\tau > t) \leq \exp \left(\rho t - \frac{(tv - R)^2}{\|\sigma\|t} \right).$$

It follows from Tonelli's theorem that

$$\mathbb{E}(e^{\rho\tau}) = \int_0^{+\infty} \rho e^{\rho t} \mathbb{P}(\tau > t) dt + 1 < +\infty$$

provided that $\rho < \frac{v^2}{\|\sigma\|}$.

In the second case, it is known (see e.g. Friedman [9, Theorem 14.10.1]) that the condition $\mathbb{E}e^{\rho\tau} < \infty$ holds for all numbers ρ that are smaller than the principal eigenvalue of the infinitesimal generator \mathcal{L} of Ξ on the set D :

$$\mathcal{L}\phi(x) = \frac{1}{2} \text{Trace} \left(\sigma(x) \sigma^*(x) D^2 \phi(x) \right),$$

where $D^2\phi$ is the Hessian matrix of $\phi \in C^2(\mathbb{R}^d)$. To derive a condition on α and R for Assumption B, we consider an auxiliary problem. The set D is contained in a ball B of radius $R/2$ and τ_B is the first exit time of Ξ from B . Clearly $\tau = \tau_D \leq \tau_B$. Hence we can consider the operator \mathcal{L} on the ball B . Moreover the principal eigenvalue of \mathcal{L} is greater than the principal eigenvalue of the operator $(\alpha/2)\Delta$. The principal eigenvalue of the Laplace operator Δ on the unit ball is given by the constant $(j_d)^2$. See [14] for details. Hence the principal eigenvalue of $(\alpha/2)\Delta$ on B is given by $\frac{2\alpha}{R^2}(j_d)^2$. Consequently, B holds if

$$\rho < \frac{2\alpha}{R^2}(j_d)^2. \quad \square$$

Remark 8 (On A3'). The bound $\frac{v^2}{\|\sigma\|}$ respectively $\frac{2\alpha}{R^2}(j_d)^2$ gives a minimal value for the parameter m in A3' (see Remark 7 and Lemma 10 in the Appendix).

Next we adapt Definition 1 to the case of a random terminal time and present the main result of this section. To this end, we set

$$\tau_\varepsilon = \inf\{t \geq 0, \text{dist}(\Xi_t) \leq \varepsilon\}, \quad (16)$$

where $\text{dist}(\Xi_t)$ denotes the distance between the position of Ξ at time t and the boundary of D .

Definition 2 (*Weak Supersolution in the Case of a Random Terminal Time*). We say that a triple of processes (Y, ψ, M) is a supersolution to the BSDE (1) with singular terminal condition $Y_\tau = \xi$ if it satisfies:

1. $M \in \mathcal{M}^\perp$, $\psi \in G_{\text{loc}}(\pi)$ and there exists some $\ell > 1$ such that for all $t \geq 0$ and $\varepsilon > 0$:

$$\mathbb{E} \left(\sup_{s \in [0, t]} |Y_{s \wedge \tau_\varepsilon}|^\ell + \int_0^{t \wedge \tau_\varepsilon} \int_{\mathcal{Z}} |\psi_s(z)|^\ell \mu(dz) ds + [M]_{t \wedge \tau_\varepsilon}^{\ell/2} \right) < +\infty;$$

2. Y is bounded from below by a process $\bar{Y} \in \mathbb{S}^2(0, \tau)$;
3. for all $0 \leq s \leq t$ and $\varepsilon > 0$:

$$Y_{s \wedge \tau_\varepsilon} = Y_{t \wedge \tau_\varepsilon} + \int_{s \wedge \tau_\varepsilon}^{t \wedge \tau_\varepsilon} f(u, Y_u, \psi_u) du - \int_{s \wedge \tau_\varepsilon}^{t \wedge \tau_\varepsilon} \int_{\mathcal{Z}} \psi_u(z) \tilde{\pi}(dz, du) - \int_{s \wedge \tau_\varepsilon}^{t \wedge \tau_\varepsilon} dM_u.$$

4. On the set $\{t \geq \tau\}$: $Y_t = \xi$, $\psi = M = 0$ a.s. and $\liminf_{t \rightarrow \tau} Y_t \geq \xi$ a.s.

We say that (Y, ψ, M) is a minimal supersolution to the BSDE (1) if for any other supersolution (Y', ψ', M') we have $Y_t \leq Y'_t$ a.s. for any $t > 0$.

Theorem 2. If τ is the exit time given by (15), under Assumptions (A') there exists a minimal supersolution (Y, ψ, M) to (1) with singular terminal condition $Y_\tau = \xi$.

As in Section 1.2 we first consider the truncated BSDE (5).

Proposition 5. Assume that Assumptions (A') hold. Then there exists for each $L > 0$ a solution $(Y^L, \psi^L, M^L) \in \mathbb{S}^2(0, \tau) \times L_\pi^2(0, \tau) \times \mathcal{M}^2(0, \tau)$ to the BSDE (5) with terminal condition $Y_\tau^L = \xi \wedge L$.

Proof. We check that all assumptions of Theorem 3 in [23] are satisfied. The driver f^L (cf. (6)) of the BSDE (5) satisfies the monotonicity condition A1

$$(f^L(t, y, \psi) - f^L(t, y', \psi))(y - y') \leq \chi |y - y'|^2$$

a.s. for any $(t, y, y', \psi) \in [0, T] \times \mathbb{R}^2 \times L_\mu^2$. Moreover, from A2, f^L is Lipschitz continuous w.r.t. ψ . By Condition A3', f^L satisfies

$$\forall j > 0, \forall n \in \mathbb{N}, \sup_{|y| \leq j} (|f^L(t, y, 0) - f^L(t, 0, 0)|) \in L^1(\Omega \times (0, n)).$$

Moreover $|\xi \wedge L|$ and $f^L(t, 0, 0) = f_t^0 \wedge L$ are bounded from Assumption A4'. The conditions B and A3' imply that there exists $r > 1$ such that

$$\delta = r \left[\chi + \frac{K^2}{2((r-1) \wedge 1)} \right] < \rho \quad \text{and} \quad \frac{r\delta}{\rho - \delta} < m$$

(see Lemma 10 in the Appendix for the proof). Hence

$$\mathbb{E} \int_0^\tau e^{\delta t} (|\xi \wedge L|^r + |f^L(t, 0, 0)|^r) dt < +\infty. \quad (17)$$

Next, let $\xi_t^L = \mathbb{E}[\xi \wedge L | \mathcal{F}_t]$ and let (Γ, l, N) be given by the martingale representation of $\xi \wedge L$

$$\xi \wedge L = \mathbb{E}[\xi \wedge L] + \int_0^\infty \Gamma_s dW_s + \int_0^\infty \int_{\mathcal{Z}} l_s(z) \tilde{\pi}(dz, ds) + N_\tau.$$

Since $\xi \wedge L$ is bounded (by L for L large enough since ξ^- is supposed to be bounded), the process ξ_t is also bounded by L . Using Conditions A1 and A2 we obtain for some constant C (depending on r) which will change from line to line:

$$\begin{aligned} \mathbb{E} \left[\int_0^\tau e^{\delta t} |f^L(t, \xi_t, l_t)|^r dt \right] &\leq C \mathbb{E} \left[\int_0^\tau e^{\delta t} |f(t, \xi_t, l_t) - f_t^0|^r dt \right] \\ &\quad + C \mathbb{E} \int_0^\tau e^{\delta t} |f_t^0 \wedge L|^r dt \\ &\leq C \mathbb{E} \left[\int_0^\tau e^{\delta t} \|l_t\|_{L_\mu^2}^r dt \right] + C \mathbb{E} \left[\int_0^\tau e^{\delta t} |U_t(L)|^r dt \right] \\ &\quad + C \mathbb{E} \int_0^\tau e^{\delta t} |f_t^0 \wedge L|^r dt. \end{aligned}$$

Since f^0 is bounded, using A4' as in Inequality (17), one can show that the last term is finite. By Hölder inequality, for any $h > 1$ and $\tilde{h} > 1$ such that $(h-1)(\tilde{h}-1) = 1$

$$\mathbb{E} \left[\int_0^\tau e^{\delta t} \|l_t\|_{L_\mu^2}^r dt \right] \leq \left(\mathbb{E} \int_0^\tau e^{\delta h t} dt \right)^{1/h} \left(\mathbb{E} \int_0^\tau \|l_t\|_{L_\mu^2}^{r\tilde{h}} dt \right)^{1/\tilde{h}}.$$

But since $\xi \wedge L$ is bounded, the process l coming from the martingale representation is in any $L_\pi^m(0, \tau)$, $m > 1$. Hence choosing h close enough to 1, this term is also finite. We proceed similarly for the remaining term:

$$\mathbb{E} \left[\int_0^\tau e^{\delta t} |U_t(L)|^r dt \right] \leq \left(\mathbb{E} \int_0^\tau e^{\delta h t} dt \right)^{1/h} \left(\mathbb{E} \int_0^\tau |U_t(L)|^{r\tilde{h}} dt \right)^{1/\tilde{h}}.$$

From Hypotheses B and A3' we can choose h and \tilde{h} such that $\delta h < \rho$ and $r\tilde{h} \leq m$.

Hence the assumptions of Theorem 3 in [23] hold and there exists a solution (Y^L, ψ^L, M^L) to the BSDE (5) with terminal condition $Y_\tau = \xi \wedge L$. More precisely for any $0 \leq t \leq T$

$$\begin{aligned} Y_{t \wedge \tau}^L &= Y_{T \wedge \tau}^L + \int_{t \wedge \tau}^{T \wedge \tau} \left[f(s, Y_s^L, \psi_s^L) + (\gamma_s \wedge L) \right] ds \\ &\quad - \int_{t \wedge \tau}^{T \wedge \tau} \int_{\mathcal{Z}} \psi_s^L(z) \tilde{\pi}(dz, ds) - \int_{t \wedge \tau}^{T \wedge \tau} dM_s^L, \end{aligned}$$

and $Y_t^L = \xi \wedge L$ on the set $\{t \geq \tau\}$. \square

Observe that the proof of Proposition 5 does not use the fact that τ is a first hitting time but works for every stopping time τ that satisfies the integrability conditions B and A3'. Moreover if we assume

$$|f(t, 0, \psi)| \leq K^f, \quad (18)$$

for some constant K^f , then in B we need simply $\rho > \chi$ (see Remark 2 in [23]).

The next example shows that further assumptions on τ are necessary in order to ensure that the family Y^L is uniformly bounded from above. Therefore we will assume the particular form (15) of τ in the sequel.

Example 1. Assume that $\tilde{f}(t, y, \psi) = -|y|^2$ and $\xi = \infty$. We assume that the filtration \mathcal{F} supports a stopping time τ such that $\mathbb{E} \left[\frac{1}{\tau} \right] = \infty$ and that satisfies the integrability conditions B

and (13). This holds for example for all stopping times that have a continuous density function f on \mathbb{R}_+ with $f(0) > 0$. In particular, one can take τ to be the first jump time of a Poisson process, in which case τ is exponentially distributed. For each $L > 0$ let Y^L denote the solution to BSDE (5) constructed in Proposition 5. Next, we derive a lower bound for Y^L . To this end let $X_t = \exp(-\int_0^t Y_s^L ds)$. From Itô's formula we obtain

$$dY_t^L X_t^2 = -(Y_t^L X_t)^2 dt + Z_t^L X_t^2 dW_t.$$

In particular, this implies $Y_0^L = \mathbb{E}[\int_0^\tau \dot{X}_s^2 ds + L X_\tau^2]$. Next, fix a realization $\omega \in \Omega$. Consider the deterministic control problem of minimizing the functional $\int_0^{\tau(\omega)} \dot{x}^2(s) ds + L x^2(\tau(\omega))$ over functions $x : [0, \tau(\omega)] \rightarrow \mathbb{R}$ starting in $x(0) = 1$ and being absolutely continuous. Using Pontryagin's maximum principle one can show that the trajectory $x(s) = \frac{\tau(\omega)-s+1/L}{\tau(\omega)+1/L}$ is optimal in this deterministic problem. In particular, it follows that

$$\int_0^{\tau(\omega)} \dot{x}^2(s) ds + L x^2(\tau(\omega)) = \frac{1}{\tau(\omega) + 1/L} \leq \int_0^{\tau(\omega)} \dot{X}_s^2(\omega) ds + L X_{\tau(\omega)}^2(\omega).$$

Taking expectations yields $Y_0^L \geq \mathbb{E}\left[\frac{1}{\tau+1/L}\right]$ and consequently we have by monotone convergence $\liminf_{L \rightarrow \infty} Y_0^L \geq \mathbb{E}\left[\frac{1}{\tau}\right] = \infty$.

The preceding example shows that we cannot expect to obtain a finite supersolution to (1) with singular terminal condition and random terminal time if the terminal time occurs too suddenly. Therefore we restrict here attention to the case where τ is the first hitting time of a diffusion. We introduce the signed distance function $\text{dist} : \mathbb{R}^d \rightarrow \mathbb{R}$ of D , which is defined by $\text{dist}(x) = \inf_{y \notin D} \|x - y\|$ if $x \in D$ and $\text{dist}(x) = -\inf_{y \in D} \|x - y\|$ if $x \notin D$. The next result is a Keller–Osseman type inequality (cf. (19) and see [21,24]): Using analytical properties of the diffusion near the boundary ∂D , allows us to bound at each time t the value of process Y_t^L against the distance of the diffusion Ξ to the boundary ∂D .

Proposition 6. *If τ is the exit time given by (15), under Assumptions (A') the solution processes Y^L constructed in Proposition 5 are bounded uniformly in L : There exists a process $\bar{Y} \in \mathbb{S}^2(0, \tau)$ and a constant C such that:*

$$\bar{Y}_{t \wedge \tau} \leq Y_{t \wedge \tau}^L \leq \frac{C}{\text{dist}(\Xi_{t \wedge \tau})^{2(p-1)}}. \quad (19)$$

Proof. First observe that the lower bound of Y^L follows as in Proposition 1 from a comparison theorem with a BSDE with terminal condition $-\xi^-$ and driver $g(t, y, \psi) = (f(t, y, \psi) - f_t^0) - (f_t^0)^-$.

For the upper bound, let $\mu > 0$ and introduce the set $D_\mu = \{x \in \mathbb{R}^d, |\text{dist}(x)| \leq \mu\}$. Then it follows from Lemma 14.16 in [11] that there exists a positive constant μ such that $\text{dist} \in C^2(D_\mu)$. Since D is bounded there exists a constant $R > 0$ such that $0 \leq \text{dist}(x) \leq R$ for all $x \in \bar{D}$. Let $\varphi \in C^\infty(\mathbb{R}^d, [0, 1])$ with $\varphi = 1$ on $\mathbb{R}^d \setminus D_\mu$ and $\varphi = 0$ on $D_{\mu/2}$. For $0 < \epsilon \leq 1$ we define a function $g \in C^2(\mathbb{R}^d, \mathbb{R}_+)$ such that $g = (1 - \varphi)\text{dist} + R\varphi + \epsilon$ on \bar{D} . Since $g \geq \epsilon$ on \bar{D} , there exists a function $\Phi \in C^2(\mathbb{R}^d, \mathbb{R}_+)$ satisfying $\Phi = Cg^{-2(p-1)}$ on \bar{D} for any $C > 0$. Observe that Φ is bounded from above by $C \text{dist}^{-2(p-1)}$. Next we apply Itô's formula to the process $\Phi(\Xi_{t \wedge \tau})$.

For every $t < \tau$ this yields

$$\begin{aligned} d\Phi(\Xi_t) &= (p-1) \frac{\Phi^q(\Xi_t)}{\eta_t^{q-1}} dt + \nabla \Phi(\Xi_t) \sigma(\Xi_t) dW_t \\ &\quad + \left(\nabla \Phi(\Xi_t) b(\Xi_t) + \frac{1}{2} \text{Trace}(\sigma \sigma^*(\Xi_t) D^2 \Phi(\Xi_t)) - (p-1) \frac{\Phi^q(\Xi_t)}{\eta_t^{q-1}} \right) dt \\ &= \left[(p-1) \frac{\Phi^q(\Xi_t)}{\eta_t^{q-1}} - f_t^0 \right] dt + \nabla \Phi(\Xi_t) \sigma(\Xi_t) dW_t \\ &\quad + \left[f_t^0 + \nabla \Phi(\Xi_t) b(\Xi_t) + \frac{1}{2} \text{Trace}(\sigma \sigma^*(\Xi_t) D^2 \Phi(\Xi_t)) - (p-1) \frac{\Phi^q(\Xi_t)}{\eta_t^{q-1}} \right] dt. \end{aligned}$$

On \bar{D} we have

$$\begin{aligned} \Phi^r &= C^q g^{-2q(p-1)} = C^q g^{-2p} \\ \nabla \Phi &= -2(p-1) C g^{-2p+1} \nabla g \\ \frac{\partial^2 \Phi}{\partial x_i \partial x_j} &= -2(p-1)(-2p+1) C g^{-2p} \frac{\partial g}{\partial x_i} \frac{\partial g}{\partial x_j} - 2(p-1) C g^{-2p+1} \frac{\partial^2 g}{\partial x_i \partial x_j}. \end{aligned}$$

For $t \leq \tau$ let

$$\begin{aligned} G_t &= \nabla \Phi(\Xi_t) b(\Xi_t) + \frac{1}{2} \text{Trace}(\sigma \sigma^*(\Xi_t) D^2 \Phi(\Xi_t)) - (p-1) \frac{\Phi^q(\Xi_t)}{\eta_t^{q-1}} \\ &= -(p-1) C g^{-2p}(\Xi_t) H(\Xi_t) \end{aligned}$$

with

$$\begin{aligned} H(\Xi_t) &= \frac{C^{p-1}}{\eta_t^{q-1}} + 2(g \nabla g b)(\Xi_t) + (-2p+1) \|\sigma(\Xi_t) \nabla g(\Xi_t)\|^2 \\ &\quad + \left[g \text{Trace}(\sigma \sigma^* D^2 g) \right](\Xi_t) \\ &\geq \frac{C^{p-1}}{\|\eta\|_\infty^{q-1}} + 2(g \nabla g b)(\Xi_t) + (-2p+1) \|\sigma(\Xi_t) \nabla g(\Xi_t)\|^2 \\ &\quad + \left[g \text{Trace}(\sigma \sigma^* D^2 g) \right](\Xi_t), \end{aligned}$$

since from condition A6', η is bounded. Now \bar{D} is a compact set. Thus the continuous functions b and σ are bounded on \bar{D} . Moreover, the functions g , ∇g and $D^2 g$ are bounded on \bar{D} uniformly in ϵ . Hence there exists $C_0 > 0$ which does not depend on ϵ such that for any $C \geq C_0$, for every $t \geq 0$ and on \bar{D} we have $H(\Xi_t) \geq 1$.

Again by Assumption A6', the process f^0 is bounded from above. Hence for some C large enough:

$$\begin{aligned} -\mathcal{G}_t &= G_t + f_t^0 = -(p-1) C g^{-2p}(\Xi_t) H(\Xi_t) + f_t^0 \leq -(p-1) C g^{-2p}(\Xi_t) + \|f^0\|_\infty \\ &\leq 0. \end{aligned}$$

Now the constant C is fixed. The process $\Phi(\Xi)$ satisfies

$$\begin{aligned}\Phi(\Xi_{t \wedge \tau}) &= \Phi(\Xi_{T \wedge \tau}) + \int_{t \wedge \tau}^{T \wedge \tau} \left[-(p-1) \frac{\Phi^q(\Xi_s)}{\eta_s^{q-1}} + f_s^0 \right] ds \\ &\quad + \int_{t \wedge \tau}^{T \wedge \tau} \mathcal{G}_s ds - \int_{t \wedge \tau}^{T \wedge \tau} \nabla \Phi(\Xi_s) \sigma(\Xi_s) dW_s\end{aligned}$$

for all $0 \leq t \leq T$, with $\mathcal{G}_s \geq 0$. Let us denote by Z the martingale

$$Z_t = \int_0^t \nabla \Phi(\Xi_s) \sigma(\Xi_s) dW_s.$$

The triple $(\Phi(\Xi), 0, Z)$ is solution of the BSDE with the generator:

$$v(t, y, \psi) = -(p-1) \frac{y|y|^{q-1}}{\eta_t^{q-1}} + f_s^0 + f(t, 0, \psi) + \mathcal{G}_t$$

and terminal condition $\Phi(\Xi_{T \wedge \tau}) = \frac{C}{\varepsilon^{2(p-1)}}$ on $\{T \geq \tau\}$. Condition A5 on f implies that

$$f^L(t, \Phi(\Xi_t), 0) \leq v(t, \Phi(\Xi_t), 0).$$

Moreover we choose ε small enough such that $L \leq C/\varepsilon^{(p-1)/2}$. Hence $Y_{T \wedge \tau}^{L,+} \leq \Phi(\Xi_{T \wedge \tau})$ on $\{T \geq \tau\}$. The comparison principle (cf. Remark 3 in [23]) leads to: for any $t \geq 0$, $Y_{t \wedge \tau}^{L,+} \leq \Phi(\Xi_{t \wedge \tau})$ and by construction $\Phi(\Xi_{t \wedge \tau}) \leq C \text{dist}^{-2(p-1)}(\Xi_{t \wedge \tau})$. This achieves the proof. \square

Now as in Section 1.2, we can define a process Y as the limit of the increasing sequence Y^L to obtain the minimal supersolution of (1). The next proposition completes the proof of Theorem 2.

Proposition 7. Suppose that τ is given by (15) and that Assumptions (A') are in force and let (Y^L, ψ^L, M^L) denote the solution of BSDE (5) obtained in Proposition 5. Then there exists a process (Y, ψ, M) such that Y_t^L converges a.s. to Y_t , ψ^L converges in $L_\pi^2(0, \tau_\varepsilon)$ to ψ and M^L converges in $\mathcal{M}^2(0, \tau_\varepsilon)$ to M for any $\varepsilon > 0$. The limit process (Y, ψ, M) is the minimal supersolution for the BSDE (1) with terminal condition ξ .

Proof. We proceed as in the proof of Proposition 3. We outline the main steps. First observe that Y_t^L converges a.s. to a limit process Y by a comparison principle (cf. Remark 3 in [23]). Recall the definition of the stopping times τ_ε , $\varepsilon > 0$, $\tau_\varepsilon = \inf\{t \geq 0, \text{dist}(I_t) \leq \varepsilon\}$. We have $\text{dist}(I_{t \wedge \tau_\varepsilon}) \geq \varepsilon$ for ε small enough. Moreover τ_ε converges to τ when ε goes to zero. Using this sequence of times τ_ε , the whole sequence (Y^L, ψ^L, M^L) converges to (Y, ψ, M) on $\mathbb{S}^2(0, \tau_\varepsilon) \times L_\mu^2(0, \tau_\varepsilon) \times \mathcal{M}^2(0, \tau_\varepsilon)$ for all $\varepsilon > 0$. The main argument is that by Proposition 6 on the interval $(0, \tau_\varepsilon)$, the process Y^L is uniformly bounded by $C/\varepsilon^{2(p-1)}$. Moreover (Y, ψ, M) satisfies for any $\varepsilon > 0$ and any $0 \leq t \leq T$

$$Y_{t \wedge \tau_\varepsilon} = Y_{T \wedge \tau_\varepsilon} + \int_{t \wedge \tau_\varepsilon}^{T \wedge \tau_\varepsilon} f(s, Y_s, \psi_s) ds - \int_{t \wedge \tau_\varepsilon}^{T \wedge \tau_\varepsilon} \int_{\mathcal{Z}} \psi_s(z) \tilde{\pi}(dz, ds) - \int_{t \wedge \tau_\varepsilon}^{T \wedge \tau_\varepsilon} dM_s.$$

Since the filtration is supposed to be left-continuous, we have a.s. $\lim_{t \rightarrow \tau} Y_t^L = \xi \wedge L$. Therefore we obtain the following behavior of Y at the terminal time $\liminf_{t \rightarrow \tau} Y_t \geq \xi$. The minimality of the solution follows by the same arguments as in Proposition 4. \square

2. Optimal position targeting

2.1. Problem formulation

Let us now describe the stochastic control problem. We assume that the setting from Section 1.1 is given. Moreover, we suppose that **the measure μ is finite**. As in Section 1 we fix some $p > 1$ and denote by $q = 1/(1 - 1/p)$ its Hölder conjugate. Let τ be a \mathbb{F} stopping time. For any $t \in \mathbb{R}_+$ and $x \in \mathbb{R}$, we denote by $\mathcal{A}(t, x)$ the set of progressively measurable processes $(X_s)_{s \geq 0}$ that satisfy the dynamics

$$X_s = x + \int_t^{s \vee t} \alpha_u du + \int_t^{s \vee t} \int_{\mathcal{Z}} \beta_u(z) \pi(dz, du) \quad (20)$$

for any $s \geq 0$ and for some $\alpha \in L^1(t, \infty)$ a.s. and $\beta \in G_{\text{loc}}(\pi)$. Observe that for all $X \in \mathcal{A}(t, x)$ it holds that $X_s = x$ for all $s \leq t$. We consider the stochastic control problem to minimize the functional²

$$J(t, X) = \mathbb{E} \left[\int_{t \wedge \tau}^{\tau} \left(\eta_s |\alpha_s|^p + \gamma_s |X_s|^p + \int_{\mathcal{Z}} \lambda_s(z) |\beta_s(z)|^p \mu(dz) \right) ds + \xi |X_{\tau}|^p \middle| \mathcal{F}_t \right] \quad (21)$$

over all $X \in \mathcal{A}(t, x)$. The random variable ξ is supposed to be non negative and may take the value ∞ with positive probability. Observe that if for $x > 0$ there exists $X \in \mathcal{A}(t, x)$ such that $J(t, X) < \infty$, then $\tau > t$ a.s. and X satisfies almost surely that

$$X_{\tau} \mathbf{1}_{\xi = \infty} = 0. \quad (22)$$

This way we impose implicitly a terminal state constraint on the set of admissible controls. For future reference we define the set \mathcal{S} by $\mathcal{S} = \{\xi = +\infty\}$. The coefficient processes $(\eta_t)_{t \geq 0}$, $(\gamma_t)_{t \geq 0}$ and $(\lambda_t)_{t \geq 0}$ are non negative progressively measurable càdlàg processes. The process λ is \mathcal{P} -measurable with values in $[0, +\infty]$.

We introduce the random field v that represents for each initial condition (t, x) the minimal value of J

$$v(t, x) = \operatorname{ess\,inf}_{X \in \mathcal{A}(t, x)} J(t, X). \quad (23)$$

Theorem 3 summarizes the main results of this section. It shows that the value function v and optimal controls of the control problem (23) are characterized by the BSDE

$$dY_t = (p-1) \frac{Y_t^q}{\eta_t^{q-1}} dt + \Theta(t, Y_t, \psi_t) dt - \gamma_t dt + \int_{\mathcal{Z}} \psi_t(z) \tilde{\pi}(dz, dt) + dM_t \quad (3)$$

with singular terminal condition ξ , where the function Θ is given by

$$\Theta(t, y, \psi) = \int_{\mathcal{Z}} (y + \psi(z)) \left(1 - \frac{\lambda_t(z)}{((y + \psi(z))^{q-1} + \lambda_t(z)^{q-1})^{p-1}} \right) \mathbf{1}_{y + \psi(z) \geq 0} \mu(dz). \quad (24)$$

² We use the convention that $0 \cdot \infty := 0$.

Again we distinguish two cases. In the first case we assume that τ is deterministic and impose some integrability assumptions on the coefficient processes $(\eta_t)_{t \geq 0}$ and $(\gamma_t)_{t \geq 0}$.

Assumption (C1). The stopping time τ is a.s. equal to a deterministic constant $T > 0$. The process η is positive, the process γ is non negative, such that for some $\ell > 1$

$$\mathbb{E} \left[\int_0^T (\eta_t + (T - t)^p \gamma_t)^\ell dt \right] < \infty \quad \text{and} \quad \mathbb{E} \left[\int_0^T \frac{1}{\eta_t^{q-1}} dt \right] < \infty. \quad \diamond$$

In the second case we assume that τ is given by (15) as the first hitting time of a diffusion. We need to impose some stronger boundedness conditions on η and γ compared to (C1).

Assumption (C2). We have $\tau = \tau_D$ and there exists $\rho > \mu(\mathcal{Z})$ such that $\mathbb{E} e^{\rho\tau} < \infty$. The processes η and γ are bounded from above, η is positive and satisfies the integrability conditions

$$\mathbb{E} \left[\int_0^n \frac{1}{\eta_t^{q-1}} dt \right] + \mathbb{E} \left[\int_0^\tau \frac{1}{\eta_t^{m(q-1)}} dt \right] < \infty \quad (25)$$

for all $n \in \mathbb{N}$ and for some m satisfying:

$$m > \frac{2\rho}{\rho - \mu(\mathcal{Z}) + (\sqrt{\rho} - \sqrt{2\mu(\mathcal{Z})}) \mathbf{1}_{\rho > 2\mu(\mathcal{Z})}}.$$

The process γ is non negative. \diamond

Lemma 2 gives sufficient conditions on the coefficients of the forward SDE (14) such that $\mathbb{E} e^{\rho\tau} < \infty$ holds.

Theorem 3. Let Assumptions (C1) or (C2) hold. Then there exists a minimal supersolution (Y, ψ, M) to (3) with singular terminal condition $Y_\tau = \xi$. Set $Y_s = \xi$ for all $s \geq \tau$. For all $(t, x) \in \mathbb{R}_+ \times \mathbb{R}$ it holds \mathbb{P} -a.s. that $v(t, x) = Y_t x^p$. Moreover, for every $(t, x) \in \mathbb{R}_+ \times \mathbb{R}$ the process X satisfying the linear dynamics

$$X_s = x - \int_t^{s \vee \tau} \left(\frac{Y_u}{\eta_u} \right)^{q-1} X_u du - \int_t^{s \vee \tau} X_u - \int_{\mathcal{Z}} \zeta_u(z) \pi(dz, du),$$

with

$$\zeta_u(z) = \frac{(Y_{u-} + \psi_u(z))^{q-1}}{[(Y_{u-} + \psi_u(z))^{q-1} + \lambda_u(z)^{q-1}]}$$

belongs to $\mathcal{A}(t, x)$, satisfies the terminal state constraint (22) if $t < \tau$ and is optimal in (23).

The optimal process X^* is given explicitly by

$$X_s^* = x \exp \left[- \int_t^{s \vee \tau} \left(\frac{Y_u}{\eta_u} \right)^{q-1} du \right] \exp \left[\int_t^{s \vee \tau} \int_{\mathcal{Z}} \ln(1 - \zeta_u(z)) \pi(dz, du) \right]. \quad (26)$$

To prove **Theorem 3** we first conclude from **Theorem 1** or **2** that there exists a minimal supersolution to (3). We then consider a variant of the minimization problem (23), where we penalize any non zero terminal state by $(\xi \wedge L)|X_\tau|^p$ and thus omit the constraint $X_\tau \mathbf{1}_S = 0$ on the set of admissible controls. We show that optimal controls for this unconstrained minimization problem admit a representation in terms of the solutions Y^L of a truncated version of (3). We then use this result to derive an optimal control for (23).

2.2. Existence of a minimal supersolution

Observe that BSDE (3) is a special case of (1) with generator f given by

$$f(t, y, \psi) = -(p-1) \frac{y|y|^{q-1}}{\eta_t^{q-1}} - \Theta(t, y, \psi) + \gamma_t.$$

Recall that in this section μ is supposed to be a finite measure, thus Θ (given by (24)) is well-defined. Here we have that $f_t^0 = f(t, 0, 0) = \gamma_t$. For simplicity we denote by ϖ the function

$$\varpi(t, y, \phi) = (y + \phi) \left(1 - \frac{\lambda_t(z)}{((y + \phi)^{q-1} + \lambda_t(z)^{q-1})^{p-1}} \right) \mathbf{1}_{y+\phi \geq 0}$$

such that

$$\Theta(t, y, \psi) = \int_{\mathcal{Z}} \varpi(t, y, \psi(z)) \mu(dz).$$

The next result is a consequence of Theorems 1 and 2.

Corollary 1. *Under Assumptions (C1) or (C2), the singular BSDE (3) has a minimal non negative weak supersolution (Y, ψ, M) .*

Proof. We have to prove that f satisfies Conditions (A) (respectively (A')) if (C1) (respectively (C2)) holds. A simple computation proves that for a fixed $(t, \psi) \in [0, T] \times L_{\mu}^2$ and $z \in \mathcal{Z}$, the function $y \mapsto \varpi(t, y, \psi(z))$ is non decreasing and of class C^1 on \mathbb{R} with a derivative bounded by 1

$$\frac{\partial \varpi}{\partial y}(t, y, \psi(z)) = \left(1 - \frac{\lambda_t(z)^q}{((y + \psi(z))^{q-1} + \lambda_t(z)^{q-1})^p} \right) \mathbf{1}_{y+\psi(z) \geq 0}.$$

Since $\eta > 0$, the condition A1 is satisfied with $\chi = 0$.

From the same argument the function ϖ is Lipschitz continuous w.r.t. $\psi(z)$ and hence we obtain

$$|\Theta(t, y, \psi) - \Theta(t, y, \psi')| \leq \int_{\mathcal{Z}} |\psi(z) - \psi'(z)| \mu(dz) \leq \mu(\mathcal{Z})^{1/2} \|\psi - \psi'\|_{L_{\mu}^2}.$$

Moreover for any $(t, y, \psi, \psi') \in [0, T] \times \mathbb{R} \times (L_{\mu}^2)^2$ we have

$$\begin{aligned} f(t, y, \psi) - f(t, y, \psi') &= -\Theta(t, y, \psi) + \Theta(t, y, \psi') \\ &= \int_{\mathcal{Z}} (\varpi(t, y, \psi'(z)) - \varpi(t, y, \psi(z))) \mu(dz) \\ &= \int_{\mathcal{Z}} (\psi(z) - \psi'(z)) \kappa_t^{y, \psi, \psi'}(z) \mu(dz) \end{aligned}$$

where

$$\kappa_t^{y, \psi, \psi'}(z) = -\frac{\varpi(t, y, \psi(z)) - \varpi(t, y, \psi'(z))}{\psi(z) - \psi'(z)} \mathbf{1}_{\psi(z) \neq \psi'(z)}.$$

Since ϖ is non decreasing in ψ with derivative bounded from above by 1, we obtain $-1 \leq \kappa_t^{y, \psi, \psi'} \leq 0$. Thus Conditions A2 and A7 hold for any $k \geq 1$. We can even note that (9) (cf.

[Lemma 1](#) and [Remark 4](#)) is true with $K_t^f = 0$. For every $r > 0$ and $|y| \leq r$ we have

$$|f(t, y, 0) - f_t^0| = (p-1) \frac{|y|^q}{\eta_t^{q-1}} + |\Theta(t, y, 0)| \leq (p-1) \frac{|r|^q}{\eta_t^{q-1}} + \mu(\mathcal{Z})|r| =: U_t(r).$$

By Assumption (C1), the mapping $t \mapsto U_t(r)$ is in $L^1((0, T) \times \Omega)$ and Condition A3 holds. Condition A4 holds since γ and ξ are non negative. Finally since $\Theta \geq 0$, Condition A5 is satisfied and A6 holds if Assumption (C1) is assumed.

A similar computation shows that under (C2), Conditions A4' and A6' hold. We have here $\chi = 0$ and $K^2 = \mu(\mathcal{Z})$, thus $\delta^* = \mu(\mathcal{Z})$ (see Eq. (11)) and therefore the assumption $\rho > \mu(\mathcal{Z})$ implies Condition B. Moreover from (25), the process $U_t(r)$ is in $L^1((0, n) \times \Omega)$ for any $n \in \mathbb{N}$ and satisfies $\mathbb{E} \int_0^\tau |U_t(r)|^m dt < +\infty$, with $m > h^*$ (see Eq. (12)). Hence [Corollary 1](#) is a direct consequence of [Theorem 1](#) or [2](#). Moreover, by [Proposition 1](#) (respectively [Proposition 5](#)) there exists a solution (Y^L, ψ^L, M^L) of the truncated BSDE

$$\begin{aligned} dY_t^L &= (p-1) \frac{(Y_t^L)^{1+q}}{\eta_t^q} dt + \Theta(t, Y_t^L, \psi_t^L) dt - (\gamma_t \wedge L) dt + \int_{\mathcal{Z}} \psi_t^L(z) \tilde{\pi}(dz, dt) \\ &\quad + dM_t^L \end{aligned} \quad (27)$$

with terminal condition $Y_\tau^L = \xi \wedge L$. The process (Y, ψ, M) is the limit as L goes to $+\infty$ of (Y^L, ψ^L, M^L) and is the minimal (super-)solution of the BSDE (3). \square

2.3. Penalization

For $L > 0$ and $(t, x) \in \mathbb{R}_+ \times \mathbb{R}$ we consider the unconstrained minimization problem:

$$\begin{aligned} v^L(t, x) &= \operatorname{essinf}_{X \in \mathcal{A}(t, x)} J^L(t, X) \\ &= \operatorname{essinf}_{X \in \mathcal{A}(t, x)} \mathbb{E} \left[\int_{t \wedge \tau}^\tau \left(\eta_s |\alpha_s|^p + (\gamma_s \wedge L) |X_s|^p + \int_{\mathcal{Z}} \lambda_s(z) |\beta_s(z)|^p \mu(dz) \right) ds \right. \\ &\quad \left. + (\xi \wedge L) |X_\tau|^p \middle| \mathcal{F}_t \right]. \end{aligned} \quad (28)$$

Proposition 8. *Let Assumption (C1) or (C2) hold and let (Y^L, ψ^L, M^L) be the solution to (27) with terminal condition $Y_\tau = \xi \wedge L$. Let $Y_s = L \wedge \xi$ for all $s \geq \tau$. Then for all $(t, x) \in \mathbb{R}_+ \times \mathbb{R}$ the process X^L satisfying the linear dynamics*

$$X_s^L = x - \int_t^{s \vee \tau} \left(\frac{Y_r^L}{\eta_r} \right)^{q-1} X_r^L dr - \int_t^{s \vee \tau} X_{r-}^L \int_{\mathcal{Z}} \zeta_r^L(z) \pi(dz, dr),$$

with

$$\zeta_r^L(z) = \frac{(Y_{r-}^L + \psi_r(z))^{q-1}}{[(Y_{r-}^L + \psi_r^L(z))^{q-1} + \lambda_r(z)^{q-1}]}$$

is optimal in (28). Moreover, we have $v^L(t, x) = Y_t^L |x|^p$.

To prove [Proposition 8](#) we will make use of the two following auxiliary results. The first lemma shows that in the case $x \geq 0$ we can without loss of generality restrict attention to

monotone strategies.³ To this end we introduce the set $\mathcal{D}(t, x)$, the subset of $\mathcal{A}(t, x)$ containing only processes X that have non increasing sample paths (i.e. $\alpha_t \leq 0$ and $\beta_t(z) \leq 0$), and that remain non negative.

Lemma 3. *Let $x \geq 0$. Every control $X \in \mathcal{A}(t, x)$ can be modified to a control $\underline{X} \in \mathcal{D}(t, x)$ such that $J^L(t, X) \geq J^L(t, \underline{X})$. In particular, $v^L(t, x) = \text{essinf}_{X \in \mathcal{D}(t, x)} J^L(t, X)$.*

Proof. For $s \geq 0$ we consider the solution of the following SDE

$$\tilde{X}_s = x - \int_t^{s \vee t} \alpha_u^- du - \int_t^{s \vee t} \int_{\mathcal{Z}} \beta_s(z)^- \pi(dz, ds),$$

where x^- denotes the negative part of x . This process is non increasing and satisfies $\tilde{X}_s \leq X_s$. Then we define

$$\underline{X}_s = \tilde{X}_s \vee 0 = (\tilde{X}_s)^+.$$

By Tanaka's formula we have

$$\underline{X}_s = x - \int_t^{s \vee t} \mathbf{1}_{\tilde{X}_u > 0} \alpha_u^- du - \int_t^{s \vee t} \int_{\mathcal{Z}} \mathbf{1}_{\tilde{X}_u > 0} (\beta_u(z)^- \wedge (\tilde{X}_u^-)^+) \pi(dz, ds).$$

We define

$$\hat{\alpha}_s = -\mathbf{1}_{\tilde{X}_s > 0} \alpha_s^-, \quad \hat{\beta}_s(z) = -\mathbf{1}_{\tilde{X}_s > 0} (\beta_s(z)^- \wedge (\tilde{X}_s^-)^+).$$

Then \underline{X} belongs to $\mathcal{D}(t, x)$. Moreover we have

$$|\hat{\alpha}_s| \leq |\alpha_s|, \quad |\hat{\beta}_s(z)| \leq |\beta_s(z)|, \quad 0 \leq \underline{X}_s \leq |X_s|$$

which implies that $J^L(t, X) \geq J^L(t, \underline{X})$. \square

The second lemma provides the dynamics of two auxiliary processes.

Lemma 4. *Let Assumptions (C1) or (C2) hold and let (Y^L, ψ^L, M^L) be the solution of (27). Let $X^L \in \mathcal{A}(t, x)$ be the strategy from Proposition 8. Then we have for $t \leq s \leq \tau$ that*

$$d \left(\eta_s |\alpha_s^L|^{p-1} \right) = (X_{s-}^L)^{p-1} dM_s^L - (\gamma_s \wedge L) |X_s^L|^{p-1} ds - \int_{\mathcal{Z}} \phi_s(z) \tilde{\pi}(dz, ds),$$

with $\phi_s(z) = Y_{s-}^L |X_{s-}^L|^{p-1} - \lambda_s(z) |\beta_s^L(z)|^{p-1}$. Moreover, we have for $t \leq s \leq \tau$

$$\begin{aligned} d(Y_s^L (X_s^L)^p) &= - \left[\eta_s |\alpha_s^L|^p + \gamma_s^L (X_s^L)^p + \int_{\mathcal{Z}} \lambda_s(z) |\beta_s^L(z)|^p \mu(dz) \right] ds \\ &\quad + (X_{s-}^L)^p dM_s^L + (X_{s-}^L)^p \int_{\mathcal{Z}} (Y_{s-}^L + \psi_s^L(z)) \left[(1 - \zeta_s^L(z))^p - 1 \right] \tilde{\pi}(dz, ds). \end{aligned}$$

³ It is straightforward to show that $v(t, x) = v(t, -x)$ for all $(t, x) \in \mathbb{R}_+ \times \mathbb{R}_+$. Therefore, we restrict attention to the case $x \geq 0$ in the sequel.

Proof. To simplify notation we set $\gamma_s^L = \gamma_s \wedge L$. Recall that X^L and Y^L satisfy the following dynamics for $t \leq s \leq \tau$

$$\begin{aligned} dX_s^L &= -\frac{(Y_s^L)^{q-1}}{\eta_s^{q-1}} X_s^L ds - \int_{\mathcal{Z}} X_{s-}^L \zeta_s^L(z) \pi(dz, ds), \\ dY_s^L &= \left[(p-1) \frac{(Y_s^L)^q}{\eta_s^{q-1}} + \vartheta(s, Y_s^L, \psi_s^L) - \gamma_s^L \right] ds + \int_{\mathcal{Z}} \psi_s^L(z) \tilde{\pi}(dz, ds) + dM_s^L. \end{aligned}$$

For $t \leq s \leq \tau$ let

$$\theta_s = \eta_s |\alpha_s^L|^{p-1} + \int_t^s \gamma_u^L |X_u^L|^{p-1} du = Y_s^L |X_s^L|^{p-1} + \int_t^s \gamma_u^L |X_u^L|^{p-1} du.$$

Applying the integration by parts formula to θ results in

$$\begin{aligned} d\theta_s &= (X_{s-}^L)^{p-1} dY_s^L + Y_{s-}^L d((X_s^L)^{p-1}) + d[Y^L, (X^L)^{p-1}]_s + \gamma_s^L |X_s^L|^{p-1} ds \\ &= (X_{s-}^L)^{p-1} dY_s^L + Y_{s-}^L (X_{s-}^L)^{p-1} \left(-(p-1) \frac{(Y_s^L)^{q-1}}{\eta_s^{q-1}} \right) ds \\ &\quad + Y_{s-}^L (X_{s-}^L)^{p-1} \int_{\mathcal{Z}} \left((1 - \zeta_s^L(z))^{p-1} - 1 \right) \mu(dz) ds \\ &\quad + Y_{s-}^L (X_{s-}^L)^{p-1} \int_{\mathcal{Z}} \left((1 - \zeta_s^L(z))^{p-1} - 1 \right) \tilde{\pi}(dz, ds) \\ &\quad + (X_{s-}^L)^{p-1} \int_{\mathcal{Z}} \psi_s^L(z) \left((1 - \zeta_s^L(z))^{p-1} - 1 \right) \pi(dz, ds) + p \gamma_s^L |X_s^L|^{p-1} ds \\ &= (X_{s-}^L)^{p-1} \Theta(s, Y_s^L, \psi_s^L) ds \\ &\quad + (X_{s-}^L)^{p-1} \int_{\mathcal{Z}} (Y_{s-}^L + \psi_s^L(z)) \left((1 - \zeta_s^L(z))^{p-1} - 1 \right) \mu(dz) ds (X_{s-}^L)^{p-1} dM_s^L \\ &\quad + (X_{s-}^L)^{p-1} \int_{\mathcal{Z}} (Y_{s-}^L + \psi_s^L(z)) \left((1 - \zeta_s^L(z))^{p-1} - 1 \right) \tilde{\pi}(dz, ds) \\ &= (X_{s-}^L)^{p-1} dM_s^L + (X_{s-}^L)^{p-1} \int_{\mathcal{Z}} (Y_{s-}^L + \psi_s^L(z)) \left((1 - \zeta_s^L(z))^{p-1} - 1 \right) \tilde{\pi}(dz, ds) \end{aligned}$$

from the definition of ζ_s^L and Θ (see Eq. (24)). Moreover we have

$$(Y_{s-}^L + \psi_s^L(z)) \left[(1 - \zeta_s^L(z))^{p-1} - 1 \right] = \lambda_s(z) \zeta_s^L(z)^{p-1} - (Y_{s-}^L + \psi_s^L(z)),$$

which yields the first claim.

For the second equation we apply the integration by parts formula to the process $Y^L(X^L)^p$ to obtain

$$\begin{aligned} d(Y_s^L(X_s^L)^p) &= (X_{s-}^L)^p dY_s^L + Y_{s-}^L d((X_s^L)^p) + d[Y^L, (X^L)^p]_s \\ &= - \left[\eta_s (X_s^L)^p \frac{(Y_s^L)^q}{\eta_s^q} + \gamma_s^L (X_s^L)^p \right] ds + (X_{s-}^L)^p dM_s^L \\ &\quad + (X_{s-}^L)^p \Theta(s, Y_s^L, \psi_s^L) ds \\ &\quad + (X_{s-}^L)^p \int_{\mathcal{Z}} (Y_{s-}^L + \psi_s^L(z)) \left[(1 - \zeta_s^L(z))^p - 1 \right] \mu(dz) ds \\ &\quad + (X_{s-}^L)^p \int_{\mathcal{Z}} (Y_{s-}^L + \psi_s^L(z)) \left[(1 - \zeta_s^L(z))^p - 1 \right] \tilde{\pi}(dz, ds). \end{aligned}$$

But note that

$$|\alpha_s^L|^p = \left| \frac{(Y_s^L)^{q-1}}{\eta_s^{q-1}} X_s^L \right|^p = \frac{(Y_s^L)^q}{\eta_s^q} (X_s^L)^p,$$

and from the very definition (24) of Θ

$$\begin{aligned} &\Theta(s, Y_s^L, \psi_s^L) + \int_{\mathcal{Z}} (Y_s^L + \psi_s^L(z)) \left[(1 - \zeta_s^L(z))^p - 1 \right] \mu(dz) \\ &= \int_{\mathcal{Z}} (Y_s^L + \psi_s^L(z)) \left[\left(\frac{\lambda_s(z)^{q-1}}{[(Y_{s-}^L + \psi_s^L(z))^{q-1} + \lambda_s(z)^{q-1}]} \right)^p \right. \\ &\quad \left. - \frac{\lambda_s(z)}{(|Y_{s-}^L + \psi_s^L(z)|^{q-1} + \lambda_s(z)^{q-1})^{p-1}} \right] \mu(dz) \\ &= - \int_{\mathcal{Z}} (Y_s^L + \psi_s^L(z)) \frac{\lambda_s(z)}{[(Y_{s-}^L + \psi_s^L(z))^{q-1} + \lambda_s(z)^{q-1}]^p} \left[(Y_s^L + \psi_s^L(z))^{q-1} \right] \mu(dz) \\ &= - \int_{\mathcal{Z}} \lambda_s(z) |\zeta_s(z)|^p \mu(dz). \quad \square \end{aligned}$$

We close this section with the proof of [Proposition 8](#).

Proof of Proposition 8. We omit the superscript L in the sequel. Let $(t, x) \in \mathbb{R}_+ \times \mathbb{R}_+$. Take another process \bar{X} in $\mathcal{D}(t, x)$. Use the convexity of the function $y \mapsto |y|^p$ and $\alpha_s \leq 0$ to obtain

$$\begin{aligned} \int_{t \wedge \tau}^{\tau} (\eta_s (|\alpha_s|^p - |\bar{\alpha}_s|^p)) ds &\leq -p \int_{t \wedge \tau}^{\tau} \eta_s |\alpha_s|^{p-1} (\alpha_s - \bar{\alpha}_s) ds \\ &= -p \int_{t \wedge \tau}^{\tau} \eta_s |\alpha_s|^{p-1} (dX_s - d\bar{X}_s) + p \int_{t \wedge \tau}^{\tau} \int_{\mathcal{Z}} \eta_s |\alpha_s|^{p-1} (\beta_s(z) - \bar{\beta}_s(z)) \pi(dz, ds) \\ &= \mathcal{I}_t^1 + \mathcal{I}_t^2. \end{aligned} \tag{29}$$

By integration by parts on the first integral and using [Lemma 4](#) and boundedness of X and \bar{X} (see [Lemma 3](#)), we obtain

$$\begin{aligned}
\mathbb{E}^{\mathcal{F}_t} \mathcal{I}_t^1 &= -p \mathbb{E}^{\mathcal{F}_t} \left[\eta_\tau |\alpha_\tau|^{p-1} (X_\tau - \bar{X}_\tau) \right] + p \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau (X_s - \bar{X}_s) d \left(\eta_s |\alpha_s|^{p-1} \right) \right] \\
&\quad - p \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau \int_{\mathcal{Z}} (\beta_s(z) - \bar{\beta}_s(z)) \phi_s(z) \pi(dz, ds) \right] \\
&= -p \mathbb{E}^{\mathcal{F}_t} \left[Y_\tau X_\tau^{p-1} (X_\tau - \bar{X}_\tau) \right] - p \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau (\gamma_s \wedge L) |X_s^L|^{p-1} (X_s - \bar{X}_s) ds \right] \\
&\quad - p \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau \int_{\mathcal{Z}} (\beta_s(z) - \bar{\beta}_s(z)) \phi_s(z) \mu(dz) ds \right]
\end{aligned}$$

where ϕ is defined as in [Lemma 4](#). Using again convexity of $y \mapsto |y|^p$ yields

$$\begin{aligned}
\mathbb{E}^{\mathcal{F}_t} \mathcal{I}_t^1 &\leq -\mathbb{E}^{\mathcal{F}_t} \left[(\xi \wedge L) (X_\tau^p - \bar{X}_\tau^p) \right] - \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau (\gamma_s \wedge L) (X_s^p - \bar{X}_s^p) ds \right] \\
&\quad - p \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau \int_{\mathcal{Z}} (\beta_s(z) - \bar{\beta}_s(z)) \phi_s(z) \mu(dz) ds \right].
\end{aligned} \tag{30}$$

Moreover we have

$$\mathbb{E}^{\mathcal{F}_t} \mathcal{I}_t^2 = p \mathbb{E}^{\mathcal{F}_t} \int_{t \wedge \tau}^\tau \int_{\mathcal{Z}} \eta_s |\alpha_s|^{p-1} (\beta_s(z) - \bar{\beta}_s(z)) \mu(dz) ds. \tag{31}$$

Now, using [\(29\)–\(31\)](#) we obtain

$$\begin{aligned}
J(t, X) - J(t, \bar{X}) &\leq \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau \int_{\mathcal{Z}} p (\beta_s(z) - \bar{\beta}_s(z)) (\phi_s(z) - \eta_s |\alpha_s|^{p-1}) \mu(dz) ds \right] \\
&\quad + \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau \int_{\mathcal{Z}} \lambda_s(z) (|\beta_s(z)|^p - |\bar{\beta}_s(z)|^p) \mu(dz) ds \right].
\end{aligned}$$

Now recall that $\eta_s |\alpha_s|^{p-1} = Y_s^L |X_s^L|^{p-1}$. From the definition of ϕ_s and from convexity of $x \mapsto |x|^p$ we obtain:

$$\begin{aligned}
J(t, X) - J(t, \bar{X}) &\leq \mathbb{E}^{\mathcal{F}_t} \left[\int_{t \wedge \tau}^\tau \int_{\mathcal{Z}} p Y_s^L (\beta_s(z) - \bar{\beta}_s(z)) \left(|X_s^L|^{p-1} - |\bar{X}_s^L|^{p-1} \right) \mu(dz) ds \right]
\end{aligned}$$

and therefore $J(t, X) - J(t, \bar{X}) \leq 0$.

It remains to verify the identity $v^L(t, x) = Y_t^L |x|^p$. But from [Lemma 4](#) we deduce that

$$\begin{aligned}
Y_t^L |x|^p &= \mathbb{E}^{\mathcal{F}_t} \int_{t \wedge \tau}^\tau \left[\eta_u |\alpha_u^L|^p + \gamma_u^L (X_u^L)^p + \int_{\mathcal{Z}} \lambda_u(z) |\beta_u^L(z)|^p \mu(dz) \right] du \\
&\quad + \mathbb{E}^{\mathcal{F}_t} (Y_\tau^L |X_\tau^L|^p) \\
&= J(t, X) = v^L(t, x). \quad \square
\end{aligned}$$

2.4. Solving the constrained problem

This section is devoted to the proof of [Theorem 3](#). For the convenience of the reader we restate the result here.

Theorem 4. Let Assumptions (C1) or (C2) hold and let (Y, ψ, M) be the minimal solution to (3) with singular terminal condition $Y_\tau = \xi$ from Corollary 1 and let $Y_s = \xi$ for all $s \geq \tau$. Then $v(t, x) = Y_t|x|^p$ for all $(t, x) \in \mathbb{R}_+ \times \mathbb{R}$. Moreover the control given by Eq. (26)

$$X_s^* = x \exp \left[- \int_t^{s \vee t} \left(\frac{Y_u}{\eta_u} \right)^{q-1} du \right] \exp \left[\int_t^{s \vee t} \int_{\mathcal{Z}} \ln(1 - \zeta_u(z)) \pi(dz, du) \right]$$

with

$$\zeta_t(z) = \frac{(Y_{t-} + \psi_t(z))^{q-1}}{[(Y_{t-} + \psi_t(z))^{q-1} + \lambda_t(z)^{q-1}]}$$

belongs to $\mathcal{A}(t, x)$, satisfies the terminal state constraint (22) if $t < \tau$ and is optimal in (23).

Proof. Let $(t, x) \in \mathbb{R}_+ \times \mathbb{R}_+$. If $\tau = T$ is deterministic, we set $\tau_\varepsilon = T - \varepsilon$ for $\varepsilon > 0$. In the case where $\tau = \tau_D$ is given by (15), the stopping time τ_ε is defined as in (16).

Observe that Y and Y^L satisfy the same dynamics before time τ_ε . Hence, the results from Lemma 4 remain to hold true if Y^L and X^L are replaced by Y and X^* . In particular, it follows that the process

$$\theta_s = Y_s |X_s^*|^{p-1} - Y_{t \wedge \tau_\varepsilon} |X_{t \wedge \tau_\varepsilon}^*|^{p-1} + \int_{t \wedge \tau_\varepsilon}^s \gamma_u |X_u^*|^{p-1} du, \quad s \geq t \wedge \tau_\varepsilon, \quad \varepsilon > 0,$$

is a non negative local martingale on the stochastic interval $[t \wedge \tau_\varepsilon, \tau]$ for any $\varepsilon > 0$. Consequently it is a non negative supermartingale and thus converges almost surely in \mathbb{R} as s goes to τ (see Chapter V.3 in [16] or Appendix in [6]). Hence

$$0 \leq X_s^* = \left(\frac{\theta_s - p \int_{t \wedge \tau_\varepsilon}^s \gamma_u |X_u^*|^{p-1} du}{p Y_{s \wedge \tau}} \right)^{q-1} \leq \left(\frac{\theta_s}{p Y_s} \right)^{q-1}.$$

Since Y satisfies the terminal condition $\liminf_{s \nearrow \tau} Y_s \mathbf{1}_S = \infty$ we have a.s. on the set $\{t < \tau\} \cap S$:

$$0 \leq X_s^* \leq \left(\frac{\theta_s}{p Y_s} \right)^{q-1} \rightarrow 0$$

when s goes τ . It follows that X satisfies (22) if $t < \tau$.

Appealing once more to Lemma 4 we observe that for $t \leq s < \tau$

$$\begin{aligned} d(Y_s (X_s^*)^p) &= -[\eta_s |\alpha_s^*|^p + \gamma_s (X_s^*)^p] ds - \int_{\mathcal{Z}} \lambda_s(z) |\beta_s^*(z)|^p \mu(dz) ds \\ &\quad + (X_{s-}^*)^p dM_s + (X_{s-}^*)^p \int_{\mathcal{Z}} (Y_{s-} + \psi_t(z)) [(1 - \zeta_s(z))^p - 1] \tilde{\pi}(dz, ds). \end{aligned}$$

Since $|X_t^*| \leq x$ we deduce for all $\varepsilon > 0$

$$\begin{aligned} Y_t |x|^p &= \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\int_t^{\tau_\varepsilon \vee t} \left\{ \eta_u |\alpha_u^*|^p + \gamma_u (X_u^*)^p + \int_{\mathcal{Z}} \lambda_u(z) |\beta_u^*(z)|^p \mu(dz) \right\} du \right. \\ &\quad \left. + Y_{\tau_\varepsilon \vee t} |X_{\tau_\varepsilon \vee t}|^p \right] + \mathbf{1}_{\{t \geq \tau\}} \xi |x|^p \\ &\geq \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\int_t^{\tau_\varepsilon \vee t} \left\{ \eta_u |\alpha_u^*|^p + \gamma_u (X_u^*)^p + \int_{\mathcal{Z}} \lambda_u(z) |\beta_u^*(z)|^p \mu(dz) \right\} du \right. \\ &\quad \left. + \mathbf{1}_{\{\xi < \infty\}} Y_{\tau_\varepsilon \vee t} |X_{\tau_\varepsilon \vee t}|^p \right] + \mathbf{1}_{\{t \geq \tau\}} J(t, X^*). \end{aligned}$$

Appealing to monotone convergence theorem yields

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\int_t^{\tau_\varepsilon \vee t} \left\{ \eta_u |\alpha_u^*|^p + \gamma_u (X_u^*)^p + \int_{\mathcal{Z}} \lambda_u(z) |\beta_u^*(z)|^p \mu(dz) \right\} du \right] \\ = \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\int_t^\tau \left\{ \eta_u |\alpha_u^*|^p + \gamma_u (X_u^*)^p + \int_{\mathcal{Z}} \lambda_u(z) |\beta_u^*(z)|^p \mu(dz) \right\} du \right]. \end{aligned}$$

Since we have $\liminf_{\varepsilon \rightarrow 0} Y_{\tau_\varepsilon} \geq \xi$ and by Fatou's lemma, we obtain⁴

$$\begin{aligned} \liminf_{\varepsilon \rightarrow 0} \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\mathbf{1}_{\{\xi < \infty\}} Y_{\tau_\varepsilon \vee t} |X_{\tau_\varepsilon \vee t}|^p \right] &\geq \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\liminf_{\varepsilon \rightarrow 0} \mathbf{1}_{\{\xi < \infty\}} Y_{\tau_\varepsilon \vee t} |X_{\tau_\varepsilon \vee t}|^p \right] \\ &\geq \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\mathbf{1}_{\{\xi < \infty\}} \xi |X_\tau|^p \right] \\ &= \mathbf{1}_{\{t < \tau\}} \mathbb{E}^{\mathcal{F}_t} \left[\xi |X_\tau|^p \right]. \end{aligned}$$

Altogether we obtain that $Y_t |x|^p \geq J(t, X^*)$. Next, note that for every $X \in \mathcal{A}(t, x)$ we have $J(t, X) \geq J^L(t, X)$. This implies $v(t, x) \geq v^L(t, x)$ for every $L > 0$. By Proposition 8 we have $Y_t^L |x|^p = v^L(t, x)$. Minimality of Y implies

$$Y_t |x|^p = \lim_{L \nearrow \infty} Y_t^L |x|^p = \lim_{L \nearrow \infty} v^L(t, x) \leq v(t, x).$$

Consequently we obtain

$$Y_t |x|^p \geq J(t, X^*) \geq v(t, x) \geq Y_t |x|^p$$

and thus optimality of X^* . \square

Acknowledgments

The authors would like to thank the referees for helpful comments and suggestions. Thomas Kruse acknowledges the financial support from the French Banking Federation through the Chaire “Markets in Transition”.

Appendix

Some details concerning the proof of Proposition 3

In this section we give the details for the proof of Proposition 3. The constant ℓ is defined in Condition A6. Let us begin with two results contained in [23]. For $\zeta \in L^\ell(\Omega)$, let $(Y, \psi, M) \in \mathbb{S}^\ell(0, T) \times L_\pi^\ell(0, T) \times \mathcal{M}^\ell(0, T)$ be the classical solution of the BSDE:

$$Y_t = \zeta + \int_t^T g(u, Y_u, \psi_u) du - \int_t^T \int_{\mathcal{Z}} \psi_u(z) \tilde{\pi}(dz, du) - \int_t^T dM_u$$

where the generator g satisfies Conditions A1, A2 and A3 and $g_t^0 = g(t, 0, 0)$ is in $\mathbb{H}^\ell(0, T)$. Again the existence and the uniqueness of (Y, ψ, M) comes from Theorem 2 in [23]. Recall that $v(x) = |x|^{-1} x \mathbf{1}_{x \neq 0}$. The first result is the Itô formula.

⁴ Recall that $0 \cdot \infty := 0$.

Lemma 5 (Corollary 1 and Remark 1 in [23]). Let $c(\ell) = \frac{\ell((\ell-1)\wedge 1)}{2}$ and $0 \leq s \leq t \leq T$, then it holds that

$$\begin{aligned} |Y_s|^\ell &\leq |Y_t|^\ell + \ell \int_s^t |Y_u|^{\ell-1} v(Y_u) g(u, Y_u, \psi_u) du - c(\ell) \int_s^t |Y_u|^{\ell-2} \mathbf{1}_{Y_u \neq 0} d[M]_u^c \\ &\quad - \ell \int_s^t |Y_{u-}|^{\ell-1} v(Y_{u-}) dM_u - \ell \int_s^t |Y_{u-}|^{\ell-1} v(Y_{u-}) \int_{\mathcal{Z}} \psi_s(z) \tilde{\pi}(dz, du) \\ &\quad - \int_s^t \int_{\mathcal{Z}} \left[|Y_{u-} + \psi_u(z)|^\ell - |Y_{u-}|^\ell - \ell |Y_{u-}|^{\ell-1} v(Y_{u-}) \psi_u(z) \right] \pi(dz, du) \\ &\quad - \sum_{s < u \leq t} \left[|Y_{u-} + \Delta M_u|^\ell - |Y_{u-}|^\ell - \ell |Y_{u-}|^{\ell-1} v(Y_{u-}) \Delta M_u \right]. \end{aligned}$$

Moreover $\int_0^t \mathbf{1}_{Y_u=0} d[M]_u^c = 0$.

The second result is the following.

Lemma 6 (Lemma 9 in [23]). If $\ell < 2$, the non decreasing processes involving the jumps of Y control the quadratic variations:

$$\begin{aligned} &\sum_{0 < u \leq t} \left[|Y_{u-} + \Delta M_u|^\ell - |Y_{u-}|^\ell - \ell |Y_{u-}|^{\ell-1} v(Y_{u-}) \Delta M_u \right] \\ &\geq c(\ell) \sum_{0 < u \leq t} |\Delta M_u|^2 \left(|Y_{u-}|^2 \vee |Y_{u-} + \Delta M_u|^2 \right)^{\ell/2-1} \mathbf{1}_{|Y_{u-}| \vee |Y_{u-} + \Delta M_u| \neq 0} \end{aligned}$$

and

$$\begin{aligned} &\int_0^t \int_{\mathcal{Z}} \left[|Y_{u-} + \psi_u(z)|^\ell - |Y_{u-}|^\ell - \ell |Y_{u-}|^{\ell-1} v(Y_{u-}) \psi_u(z) \right] \pi(dz, du) \\ &\geq c(\ell) \int_0^t \int_{\mathcal{Z}} |\psi_u(z)|^2 \left(|Y_{u-}|^2 \vee |Y_{u-} + \psi_u(z)|^2 \right)^{\ell/2-1} \mathbf{1}_{|Y_{u-}| \vee |Y_{u-} + \psi_u(z)| \neq 0} \pi(dz, du). \end{aligned}$$

The main step in the proof of Proposition 3 is the convergence of the solution (Y^L, ψ^L, M^L) of the BSDE (5) with terminal condition $\xi^L = \xi \wedge L$. In order to carry out this step, we need suitable a priori estimates for the difference $Y^L - Y^N$. We proceed as in Proposition 3 in [23]. These are established in Lemma 9. Let $0 \leq s \leq t < T$. For L and N non negative, we put

$$\widehat{Y}_s = Y_s^N - Y_s^L, \quad \widehat{\psi}_s(z) = \psi_s^N(z) - \psi_s^L(z), \quad \widehat{M}_s = M_s^N - M_s^L.$$

W.l.o.g. we may assume that $\ell \leq 2$ and we choose $a = \ell \|\vartheta\|_{L_\mu^2}^2 / (\ell - 1)$. Then Itô's formula (see Lemma 5) implies

$$\begin{aligned} e^{as} |\widehat{Y}_s|^\ell &\leq e^{at} |\widehat{Y}_t|^\ell - \int_s^t a e^{au} |\widehat{Y}_u|^\ell du \\ &\quad + \ell \int_s^t e^{au} |\widehat{Y}_u|^{\ell-1} v(\widehat{Y}_u) (f^N(u, Y_u^N, \psi_u^N) - f^L(u, Y_u^L, \psi_u^L)) du \\ &\quad - \ell \int_s^t e^{au} |\widehat{Y}_{u-}|^{\ell-1} v(\widehat{Y}_{u-}) d\widehat{M}_u - \ell \int_s^t e^{au} |\widehat{Y}_{u-}|^{\ell-1} v(\widehat{Y}_{u-}) \int_{\mathcal{Z}} \widehat{\psi}_u(z) \tilde{\pi}(dz, du) \\ &\quad - \int_s^t e^{au} \int_{\mathcal{Z}} \left[|\widehat{Y}_{u-} + \widehat{\psi}_u(z)|^\ell - |\widehat{Y}_{u-}|^\ell - \ell |\widehat{Y}_{u-}|^{\ell-1} v(\widehat{Y}_{u-}) \widehat{\psi}_u(z) \right] \pi(dz, du) \end{aligned}$$

$$\begin{aligned}
& - \sum_{0 \leq s \leq t} e^{au} \left[|\widehat{Y}_{u-} + \Delta \widehat{M}_u|^\ell - |\widehat{Y}_{u-}|^\ell - \ell |\widehat{Y}_{u-}|^{\ell-1} \nu(\widehat{Y}_{u-}) \Delta \widehat{M}_u \right] \\
& - c(\ell) \int_s^t e^{au} |\widehat{Y}_u|^{\ell-2} \mathbf{1}_{\widehat{Y}_u \neq 0} d[\widehat{M}]_u^c.
\end{aligned} \tag{32}$$

Here $\nu(x) = |x|^{-1} x \mathbf{1}_{x \neq 0}$ and $c(\ell) = \ell(\ell-1)/2$. For the term containing the generators we have

$$\begin{aligned}
& |\widehat{Y}_u|^{\ell-1} \nu(\widehat{Y}_u) (f^N(u, Y_u^N, \psi_u^N) - f^L(u, Y_u^L, \psi_u^L)) \\
& \leq |\widehat{Y}_u|^{\ell-1} \nu(\widehat{Y}_u) (f^N(u, Y_u^N, \psi_u^N) - f^L(u, Y_u^N, \psi_u^N)) \\
& \quad + |\widehat{Y}_u|^{\ell-1} \nu(\widehat{Y}_u) (f^L(u, Y_u^N, \psi_u^N) - f^L(u, Y_u^L, \psi_u^L)) \\
& \leq |\widehat{Y}_u|^{\ell-1} \nu(\widehat{Y}_u) (f_u^0 \wedge N - f_u^0 \wedge L) \\
& \quad + |\widehat{Y}_u|^{\ell-1} \nu(\widehat{Y}_u) (f^L(u, Y_u^N, \psi_u^N) - f^L(u, Y_u^L, \psi_u^L)) \\
& \leq |\widehat{Y}_u|^{\ell-1} |f_u^0 \wedge N - f_u^0 \wedge L| + |\widehat{Y}_u|^{\ell-1} \left| \int_{\mathcal{Z}} \widehat{\psi}_u(z) \kappa_u^{Y_u^N, \psi_u^N, \psi_u^L}(z) \mu(dz) \right| \\
& \leq |\widehat{Y}_u|^{\ell-1} |f_u^0 \wedge N - f_u^0 \wedge L| + \|\vartheta\|_{L_\mu^2} |\widehat{Y}_u|^{\ell-1} \|\widehat{\psi}_u\|_{L_\mu^2}
\end{aligned}$$

where we used monotonicity A1 of f^L w.r.t. y (with $\chi = 0$) and the condition A2 of f^L w.r.t. ψ . Then by Young's inequality

$$\ell \|\vartheta\|_{L_\mu^2} |\widehat{Y}_u|^{\ell-1} \|\widehat{\psi}_u\|_{L_\mu^2} \leq \frac{\ell}{(\ell-1)} \|\vartheta\|_{L_\mu^2}^2 |\widehat{Y}_u|^\ell + \frac{c(\ell)}{2} |\widehat{Y}_u|^{\ell-2} \|\widehat{\psi}_u\|_{L_\mu^2}^2.$$

We define

$$X = e^{at} |\widehat{Y}_t|^\ell + \ell \int_0^t e^{au} |\widehat{Y}_u|^{\ell-1} |f_u^0 \wedge N - f_u^0 \wedge L| du.$$

From Lemma 6 we obtain for every $s \in [0, t]$:

$$\begin{aligned}
& e^{as} |\widehat{Y}_s|^\ell + c(\ell) \sum_{s < u \leq t} e^{au} |\Delta \widehat{M}_u|^2 \left(|\widehat{Y}_{u-}|^2 \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u|^2 \right)^{\ell/2-1} \mathbf{1}_{|\widehat{Y}_{u-}| \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u| \neq 0} \\
& + c(\ell) \int_s^t e^{au} \int_{\mathcal{Z}} |\widehat{\psi}_u(z)|^2 \left(|\widehat{Y}_{u-}|^2 \vee |\widehat{Y}_{u-} \right. \\
& \quad \left. + \widehat{\psi}_u(z)|^2 \right)^{\ell/2-1} \mathbf{1}_{|\widehat{Y}_{u-}| \vee |\widehat{Y}_{u-} + \widehat{\psi}_u(z)| \neq 0} \pi(dz, du) \\
& + c(\ell) \int_s^t e^{au} |\widehat{Y}_u|^{\ell-2} \mathbf{1}_{\widehat{Y}_u \neq 0} d[\widehat{M}]_u^c - \frac{c(\ell)}{2} \int_s^t |\widehat{Y}_u|^{\ell-2} \|\widehat{\psi}_u\|_{L_\mu^2}^2 du \\
& \leq X - \ell \int_s^t e^{au} |\widehat{Y}_{u-}|^{\ell-1} \nu(\widehat{Y}_{u-}) d\widehat{M}_u - \ell \int_s^t e^{au} |\widehat{Y}_{u-}|^{\ell-1} \nu(\widehat{Y}_{u-}) \int_{\mathcal{Z}} \widehat{\psi}_u(z) \widetilde{\pi}(dz, du).
\end{aligned} \tag{33}$$

Indeed from the choice of a , the terms

$$\frac{\ell \|\vartheta\|_{L_\mu^2}^2}{\ell-1} \int_s^t e^{au} |\widehat{Y}_u|^\ell du = a \int_s^t e^{au} |\widehat{Y}_u|^\ell du$$

cancel each other.

Lemma 9 is a consequence of the following two lemmas.

Lemma 7. *There exists a constant C_ℓ depending only on ℓ such that for any $0 < t < T$*

$$\mathbb{E} \left(\sup_{s \in [0, t]} e^{as} |\widehat{Y}_s|^\ell \right) \leq C_\ell \mathbb{E}(X). \quad (34)$$

Proof. Indeed we take τ_k as a fundamental sequence of stopping times for the local martingale

$$\int_0^\cdot e^{au} |\widehat{Y}_{u-}|^{\ell-1} \nu(\widehat{Y}_{u-}) \left(d\widehat{M}_u + \int_{\mathcal{Z}} \widehat{\psi}_u(z) \widetilde{\pi}(dz, du) \right)$$

and $\hat{\tau}_k$ as a localization time

$$\hat{\tau}_k = \inf \left\{ t \geq 0, \int_0^t \int_{\mathcal{Z}} e^{au} |\widehat{\psi}_u(z)|^2 \left(|\widehat{Y}_{u-}|^2 \vee |\widehat{Y}_u|^2 \right)^{\ell/2-1} \mathbf{1}_{|\widehat{Y}_{u-}| \vee |\widehat{Y}_u| \neq 0} \pi(dz, du) \geq k \right\}.$$

We set $\tau = \tau_k \wedge \hat{\tau}_k \wedge t$. Now we have:

$$\begin{aligned} & \mathbb{E} \int_0^\tau e^{au} \int_{\mathcal{U}} |\widehat{\psi}_s(u)|^2 \left(|\widehat{Y}_{s-}|^2 \vee |\widehat{Y}_{s-} + \widehat{\psi}_s(u)|^2 \right)^{p/2-1} \mathbf{1}_{|\widehat{Y}_{s-}| \vee |\widehat{Y}_{s-} + \widehat{\psi}_s(u)| \neq 0} \pi(du, ds) \\ &= \mathbb{E} \int_0^\tau e^{au} \int_{\mathcal{U}} |\widehat{\psi}_s(u)|^2 \left(|\widehat{Y}_{s-}|^2 \vee |\widehat{Y}_s|^2 \right)^{p/2-1} \mathbf{1}_{|\widehat{Y}_{s-}| \vee |\widehat{Y}_s| \neq 0} \pi(du, ds) \\ &= \mathbb{E} \int_0^\tau e^{au} \int_{\mathcal{U}} |\widehat{\psi}_s(u)|^2 |\widehat{Y}_s|^{p-2} \mathbf{1}_{\widehat{Y}_s \neq 0} \mu(du) ds = \mathbb{E} \int_0^\tau e^{au} \|\widehat{\psi}_s\|_{L_\mu^2}^2 |\widehat{Y}_s|^{p-2} \mathbf{1}_{\widehat{Y}_s \neq 0} ds. \end{aligned}$$

From this equality and taking the expectation in (33) we deduce that

$$\begin{aligned} & c(\ell) \mathbb{E} \sum_{0 < u \leq \tau} e^{au} |\Delta \widehat{M}_u|^2 \left(|\widehat{Y}_{u-}|^2 \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u|^2 \right)^{\ell/2-1} \mathbf{1}_{|\widehat{Y}_{u-}| \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u| \neq 0} \\ &+ c(\ell) \mathbb{E} \int_0^\tau e^{au} |\widehat{Y}_u|^{\ell-2} \mathbf{1}_{\widehat{Y}_u \neq 0} d[\widehat{M}]_u^c + \frac{c(\ell)}{2} \mathbb{E} \int_0^\tau e^{au} |\widehat{Y}_u|^{\ell-2} \|\widehat{\psi}_u\|_{L_\mu^2}^2 du \\ &+ \frac{c(\ell)}{2} \mathbb{E} \int_0^\tau e^{au} \int_{\mathcal{Z}} |\widehat{\psi}_u(z)|^2 \left(|\widehat{Y}_{u-}|^2 \vee |\widehat{Y}_{u-} \right. \\ &\quad \left. + \widehat{\psi}_u(z)|^2 \right)^{\ell/2-1} \mathbf{1}_{|\widehat{Y}_{u-}| \vee |\widehat{Y}_{u-} + \widehat{\psi}_u(z)| \neq 0} \pi(dz, du) \\ &\leq 2\mathbb{E}(X) \end{aligned} \quad (35)$$

and we can allow τ to be equal to t in this last inequality. Then using the Burkholder–Davis–Gundy inequality in (33) we obtain that:

$$\mathbb{E} \left(\sup_{0 \leq s \leq t} e^{as} |\widehat{Y}_s|^\ell \right) \leq \mathbb{E}(X) + k_\ell \mathbb{E} \left([M^Y]_t^{1/2} + [\widetilde{\pi}^Y]_t^{1/2} \right)$$

with

$$\begin{aligned} M_s^Y + \widetilde{\pi}_s^Y &= \ell \int_0^s e^{au} |\widehat{Y}_{u-}|^{\ell-1} \nu(\widehat{Y}_{u-}) d\widehat{M}_u \\ &\quad + \ell \int_0^s e^{au} |\widehat{Y}_{u-}|^{\ell-1} \nu(\widehat{Y}_{u-}) \int_{\mathcal{Z}} \widehat{\psi}_u(z) \widetilde{\pi}(dz, du). \end{aligned}$$

Since $\ell > 1$, the bracket of the first martingale is controlled by:

$$\begin{aligned} & k_\ell \mathbb{E} \left([M^Y]_t^{1/2} \right) \\ & \leq k_\ell \mathbb{E} \left[\left(\int_0^t e^{2au} \left(|\widehat{Y}_{u-}|^2 \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u|^2 \right)^{\ell-1} \mathbf{1}_{|\widehat{Y}_{u-}| \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u| \neq 0} d[\widehat{M}]_u \right)^{1/2} \right] \\ & \leq \frac{1}{4} \mathbb{E} \left(\sup_{0 \leq u \leq t} e^{au} |\widehat{Y}_u|^\ell \right) + k_\ell^2 \mathbb{E} \left(\int_0^T e^{au} |\widehat{Y}_{u-}|^{\ell-2} \mathbf{1}_{|\widehat{Y}_{u-}| \neq 0} d[\widehat{M}]_u^c \right) \\ & \quad + k_\ell^2 \mathbb{E} \left(\sum_{0 \leq s \leq T} e^{as} \left(|\widehat{Y}_{u-}|^2 \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u|^2 \right)^{\ell/2-1} \mathbf{1}_{|\widehat{Y}_{u-}| \vee |\widehat{Y}_{u-} + \Delta \widehat{M}_u| \neq 0} |\Delta \widehat{M}_u|^2 \right) \end{aligned}$$

and for the second

$$\begin{aligned} & k_\ell \mathbb{E} \left([\widetilde{\pi}^Y]_t^{1/2} \right) \\ & \leq k_\ell \mathbb{E} \left[\left(\sup_{0 \leq u \leq t} \left(e^{au} |\widehat{Y}_u|^\ell \right) \right)^{\frac{1}{2}} \left(\int_0^t e^{au} |Y_u|^{\ell-2} \mathbf{1}_{Y_u \neq 0} \int_{\mathcal{Z}} |\psi_u(z)|^2 \pi(dz, ds) \right)^{\frac{1}{2}} \right] \\ & \leq \frac{1}{4} \mathbb{E} \left(\sup_{0 \leq u \leq t} e^{au} |\widehat{Y}_u|^\ell \right) + k_p^2 \mathbb{E} \left(\int_0^t e^{au} |Y_u|^{\ell-2} \|\psi_u\|_{L_\mu^2}^2 \mathbf{1}_{Y_u \neq 0} du \right). \end{aligned}$$

Hence Inequality (34) is proved. \square

We apply again Young's inequality to obtain that

$$C_\ell \mathbb{E}(X) \leq C_\ell \mathbb{E} \left(e^{at} |\widehat{Y}_t|^\ell \right) + \frac{1}{2} \mathbb{E} \left(\sup_{s \in [0, t]} e^{as} |\widehat{Y}_s|^\ell \right) + \bar{C}_\ell \mathbb{E} \int_0^t e^{au} |f_u^0 \wedge N - f_u^0 \wedge L|^\ell du \quad (36)$$

and we can conclude that

$$\mathbb{E} \left(\sup_{s \in [0, t]} e^{as} |\widehat{Y}_s|^\ell \right) \leq \hat{C}_\ell \mathbb{E} \left(e^{at} |\widehat{Y}_t|^\ell \right) + \hat{C}_\ell \mathbb{E} \int_0^t e^{au} |f_u^0 \wedge N - f_u^0 \wedge L|^\ell du. \quad (37)$$

Next, we derive a similar inequality for ψ^L and M^L .

Lemma 8. *There exists a constant \widetilde{C}_ℓ such that for any $0 < t < T$*

$$\mathbb{E} \left[\left(\int_0^t e^{2as/\ell} d[\widehat{M}]_s \right)^{\ell/2} + \left(\int_0^t e^{2as/\ell} \int_{\mathcal{Z}} |\psi_s(z)|^2 \mu(dz) ds \right)^{\ell/2} \right] \leq \widetilde{C}_\ell \mathbb{E}(X).$$

Proof. From Lemma 5, it holds a.s.

$$\int_0^t \mathbf{1}_{\widehat{Y}_s=0} d[\widehat{M}]_s^c = 0.$$

Hence

$$\begin{aligned} \mathbb{E} \left[\left(\int_0^t e^{2as/\ell} d[\widehat{M}]_s^c \right)^{\ell/2} \right] &= \mathbb{E} \left[\left(\int_0^t e^{2as/\ell} \mathbf{1}_{Y_s \neq 0} d[\widehat{M}]_s^c \right)^{\ell/2} \right] \\ &\leq \mathbb{E} \left[\left(\sup_{0 \leq u \leq t} e^{au} |\widehat{Y}_u|^\ell \right)^{(2-\ell)/2} \left(\int_0^t e^{as} |\widehat{Y}_s|^{\ell-2} \mathbf{1}_{\widehat{Y}_s \neq 0} d[\widehat{M}]_s^c \right)^{\ell/2} \right] \\ &\leq \frac{2-\ell}{2} \mathbb{E} \left[\sup_{0 \leq u \leq t} e^{au} |\widehat{Y}_u|^\ell \right] + \frac{\ell}{2} \mathbb{E} \int_0^t e^{as} |\widehat{Y}_s|^{\ell-2} \mathbf{1}_{\widehat{Y}_s \neq 0} d[\widehat{M}]_s^c \end{aligned}$$

where we have used Hölder's and Young's inequality with $\frac{2-\ell}{2} + \frac{\ell}{2} = 1$. With Inequality (35) we deduce:

$$\mathbb{E} \left[\left(\int_0^t e^{2as/\ell} d[\widehat{M}]_s^c \right)^{\ell/2} \right] \leq \widetilde{C}_p \mathbb{E}(X).$$

For the pure-jump part of $[M]$, let $\varepsilon > 0$ and consider the function $u_\varepsilon(y) = (|y|^2 + \varepsilon^2)^{1/2}$. Then

$$\begin{aligned} \mathbb{E} \left[\left(\sum_{0 < s \leq t} e^{2as/\ell} |\Delta \widehat{M}_s|^2 \right)^{\ell/2} \right] &\leq \mathbb{E} \left[\left(\sup_{0 \leq s \leq t} e^{as/\ell} u_\varepsilon(\widehat{Y}_s) \right)^{\ell(2-\ell)/2} \right. \\ &\quad \times \left. \left(\sum_{0 < s \leq t} e^{as} (u_\varepsilon(|\widehat{Y}_{s-}| \vee |\widehat{Y}_{s-} + \Delta \widehat{M}_s|))^{\ell-2} |\Delta \widehat{M}_s|^2 \right)^{\ell/2} \right] \\ &\leq \left\{ \mathbb{E} \left[\left(\sup_{0 \leq s \leq t} e^{as/\ell} u_\varepsilon(\widehat{Y}_s) \right)^\ell \right] \right\}^{(2-\ell)/2} \\ &\quad \times \left\{ \mathbb{E} \left(\sum_{0 < s \leq t} e^{as} (u_\varepsilon(|\widehat{Y}_{s-}| \vee |\widehat{Y}_{s-} + \Delta \widehat{M}_s|))^{\ell-2} |\Delta \widehat{M}_s|^2 \right) \right\}^{\ell/2} \\ &\leq \frac{2-\ell}{2} \mathbb{E} \left[\sup_{0 \leq s \leq t} e^{as} u_\varepsilon(\widehat{Y}_s)^\ell \right] \\ &\quad + \frac{\ell}{2} \mathbb{E} \left(\sum_{0 < s \leq t} e^{as} (u_\varepsilon(|\widehat{Y}_{s-}| \vee |\widehat{Y}_{s-} + \Delta \widehat{M}_s|))^{\ell-2} |\Delta \widehat{M}_s|^2 \right). \end{aligned}$$

Let ε go to zero with Inequality (35)

$$\begin{aligned} \mathbb{E} \left[\left(\sum_{0 < s \leq t} e^{2as/\ell} |\Delta \widehat{M}_s|^2 \right)^{\ell/2} \right] &\leq \frac{2-\ell}{2} \mathbb{E} \left(\sup_{0 \leq s \leq t} e^{as} |\widehat{Y}_s|^\ell \right) \\ &\quad + \frac{\ell}{2} \mathbb{E} \left(\sum_{0 < s \leq t} e^{as} (|\widehat{Y}_{s-}| \vee |\widehat{Y}_{s-} + \Delta \widehat{M}_s|)^{\ell-2} \mathbf{1}_{|\widehat{Y}_{s-}| \vee |\widehat{Y}_{s-} + \Delta \widehat{M}_s| \neq 0} |\Delta \widehat{M}_s|^2 \right) \\ &\leq \widetilde{C}_\ell \mathbb{E}(X). \end{aligned}$$

The same argument shows that

$$\mathbb{E} \left[\left(\int_0^t e^{2as/\ell} \int_{\mathcal{Z}} |\psi_s(z)|^2 \mu(dz) ds \right)^{\ell/2} \right] \leq \tilde{C}_\ell \mathbb{E}(X). \quad \square$$

Combining estimates of [Lemmas 7](#) and [8](#) with Inequalities [\(36\)](#) and [\(37\)](#) we obtain the desired result:

Lemma 9. *There exists a constant K_ℓ such that for any $0 < t < T$*

$$\begin{aligned} & \mathbb{E} \left[\sup_{s \in [0, t]} e^{as} |\widehat{Y}_s|^\ell + \left(\int_0^t e^{2as/\ell} \int_{\mathcal{Z}} |\widehat{\psi}_u(z)|^2 \mu(dz) du \right)^{\ell/2} + \left(\int_0^t e^{2as/\ell} d[\widehat{M}]_s \right)^{\ell/2} \right] \\ & \leq K_\ell \mathbb{E} \left(e^{at} |\widehat{Y}_t|^\ell \right) + K_\ell \mathbb{E} \left(\int_0^t e^{au} |f_u^0 \wedge N - f_u^0 \wedge L|^\ell du \right) \end{aligned}$$

where K_ℓ depends only on ℓ .

Some details concerning the conditions B and $A3'$

Recall that δ^* and h^* are defined by the formulas [\(11\)](#) and [\(12\)](#).

Lemma 10. *If $\rho > \delta^*$ and $m > h^*$, then there exists $r > 1$ such that*

$$r \left[\chi + \frac{K^2}{2((r-1) \wedge 1)} \right] < \rho \quad \text{and} \quad \frac{r\delta}{\rho - \delta} < m.$$

Proof. Let us define the function $\delta: (1, \infty) \rightarrow \mathbb{R}$,

$$\delta(r) = r \left[\chi + \frac{K^2}{2((r-1) \wedge 1)} \right].$$

We show that δ^* is the minimal value of δ . We first assume that $K \neq 0$. Then $\lim_{r \rightarrow 1} \delta(r) = +\infty$.

- **Case 1:** $\chi < -K^2/2$. δ is decreasing and tends to $-\infty$ as r tends to $+\infty$. Thus $\delta^* = -\infty$.
- **Case 2:** $\chi = -K^2/2$. δ is a non increasing function with $\delta(r) > 0$ for any $r < 2 = r^*$ and $\delta(r) = 0$ for any $r \geq 2 = r^*$. Hence $\delta^* = 0$.
- **Case 3:** $\chi > -K^2/2$. The function δ tends to $+\infty$ when r tends to $+\infty$ and has a strict minimum at $r^* \in [1, 2]$:

$$r^* = 1 + \left(\mathbf{1}_{-\frac{K^2}{2} < \chi \leq \frac{K^2}{2}} + \frac{K}{\sqrt{2\chi}} \mathbf{1}_{\chi > \frac{K^2}{2}} \right).$$

Moreover the minimum $\delta^* = \delta(r^*) > 0$ is given by:

$$\delta^* = \begin{cases} 2 \left(\chi + \frac{K^2}{2} \right) = K^2 + 2\chi & \text{if } -K^2 < 2\chi \leq K^2, \\ \chi \left(1 + \frac{K}{\sqrt{2\chi}} \right)^2 = \chi(r^*)^2 & \text{if } 2\chi > K^2. \end{cases}$$

Gathering together the above results implies that δ^* defined in Eq. [\(11\)](#) is the minimal value of δ .

Therefore if $\rho > \delta^*$ (Condition (B)), there exists an open interval (R_1, R_2) such that for any $r \in (R_1, R_2)$, $\rho > \delta(r) \geq \delta^*$. In Case 1, we have $1 < R_1$ and $R_2 = +\infty$; in Case 2, $1 < R_1 < 2$ and $R_2 = +\infty$, and in Case 3, $1 < R_1 < r^* < R_2 < +\infty$. Let us define on (R_1, R_2) the function

$$h(r) = \frac{\rho r}{\rho - \delta(r)}.$$

- **Case 1:** here $R_2 = +\infty$, $\delta^* = -\infty$. The optimal choice of ρ is $\rho < 0$ (see Remark 7). Then for any $r \in (R_1, +\infty)$, $h(r) \leq 0 < m$.

In the other cases we will prove that the minimum value of h on (R_1, R_2) is h^* . Hence if $m > h^*$ (Condition A3'), there exists a value $r \in (R_1, R_2)$ such that $m > h(r) \geq h^*$ and since $\rho > \delta(r)$ on this interval, the lemma is proved.

Note that $\lim_{r \rightarrow R_1} h(r) = +\infty$ and $\rho > 0$ since $\delta^* \geq 0$. The derivative of h (except for $r = 2$) is equal to

$$h'(r) = \frac{\rho}{(\rho - \delta(r))^2} (\rho - \delta(r) + r\delta'(r)).$$

For $r > 2$, $h'(r) = \rho^2/(\rho - \delta(r))^2 > 0$. For $1 < r < 2$, we have

$$\begin{aligned} h'(r) &= \frac{\rho}{(\rho - \delta(r))^2} \left(\rho - \frac{K^2}{2} \frac{r^2}{(r-1)^2} \right) \\ &= \frac{\rho}{(\rho - \delta(r))^2} \left(\sqrt{\rho} - \frac{Kr}{\sqrt{2}(r-1)} \right) \left(\sqrt{\rho} + \frac{Kr}{\sqrt{2}(r-1)} \right). \end{aligned}$$

Therefore for some $r^\dagger \in (1, 2)$, $h'(r^\dagger) = 0$ if and only if:

$$\frac{\sqrt{2\rho}}{K} = \frac{r^\dagger}{r^\dagger - 1} \Leftrightarrow \rho > 2K^2 \quad \text{and} \quad r^\dagger = 1 + \frac{K}{\sqrt{2\rho} - K} \in (1, 2).$$

From the convexity of δ if r^\dagger exists, then $R_1 < r^\dagger < R_2$ and

$$h(r^\dagger) = -\frac{\rho}{\delta'(r^\dagger)} = \frac{2\rho}{(\sqrt{2\rho} - K)^2 - 2\chi}.$$

- **Case 2:** here $\chi + K^2/2 = 0$, $R_2 = +\infty$. If $\rho \leq 2K^2$ the minimal value of h is attained at $r = 2$, with $h^* = 2$. If $\rho > 2K^2$, then

$$h^* = h(r^\dagger) = \frac{2\rho}{(\sqrt{2\rho} - K)^2 - 2\chi} = \frac{2\rho}{(\sqrt{2\rho} - K)^2 + K^2} = \frac{2\rho}{\rho + (\sqrt{\rho} - K\sqrt{2})^2}.$$

- **Case 3:** here $\rho > \delta^* > 0$ and $1 < R_1 < R_2 < +\infty$.

a. $\chi < K^2/2$: then $R_2 > 2$. If $\delta^* = K^2 + 2\chi < \rho < 2K^2$, then

$$h^* = h(2) = \frac{2\rho}{\rho - (K^2 + 2\chi)}.$$

Else if $\rho > 2K^2$ then

$$\begin{aligned} h^* = h(r^\dagger) &= \frac{2\rho}{(\sqrt{2\rho} - K)^2 - 2\chi} = \frac{2\rho}{(\sqrt{2\rho} - K)^2 + K^2 - (K^2 + 2\chi)} \\ &= \frac{2\rho}{\rho + (\sqrt{\rho} - K\sqrt{2})^2 - (K^2 + 2\chi)}. \end{aligned}$$

Finally

$$h^* = \frac{2\rho}{\rho - (K^2 + 2\chi) + (\sqrt{\rho} - K\sqrt{2})^2 \mathbf{1}_{\rho > 2K^2}}.$$

b. $\chi \geq K^2/2$. Then $\delta^* \geq 2K^2$. Hence $\rho > 2K^2$. Thus the minimum of h is attained at $h(r^\dagger)$:

$$\begin{aligned} h^* = h(r^\dagger) &= \frac{2\rho}{(\sqrt{2\rho} - K)^2 - 2\chi} = \frac{\rho}{\left(\sqrt{\rho} - \sqrt{\chi} - \frac{K}{\sqrt{2}}\right)\left(\sqrt{\rho} + \sqrt{\chi} - \frac{K}{\sqrt{2}}\right)} \\ &= \frac{\rho}{\sqrt{\rho} + \sqrt{\chi} - \frac{K}{\sqrt{2}}} \times \frac{1}{\sqrt{\rho} - \left(\sqrt{\chi} + \frac{K}{\sqrt{2}}\right)}. \end{aligned}$$

Let us now summarize the results. h^* is given by (see also Eq. (12)):

$$h^* = \begin{cases} 0 & \text{if } 2\chi < -K^2, \\ \frac{2\rho}{\rho - \delta^* + (\sqrt{\rho} - K\sqrt{2})^2 \mathbf{1}_{\rho > 2K^2}} & \text{if } 2|\chi| \leq K^2, \\ \frac{\rho}{\sqrt{\rho} + \sqrt{\chi} - \frac{K}{\sqrt{2}}} \times \frac{1}{\sqrt{\rho} - \sqrt{\delta^*}} & \text{if } 2\chi > K^2. \end{cases}$$

Note for $K = 0$ that the formula (11) still holds and for $\chi = 0$, $h^* = 1$ and for $\chi > 0$, $h^* = \rho/(\rho - \chi)$. \square

References

- [1] R. Almgren, Optimal trading with stochastic liquidity and volatility, *SIAM J. Financ. Math.* 3 (1) (2012) 163–181.
- [2] R. Almgren, N. Chriss, Optimal execution of portfolio transactions, *J. Risk* 3 (2001) 5–40.
- [3] S. Ankirchner, M. Jeanblanc, T. Kruse, BSDEs with singular terminal condition and a control problem with constraints, *SIAM J. Control Optim.* 52 (2) (2014) 893–913.
- [4] S. Ankirchner, T. Kruse, Optimal position targeting with stochastic linear-quadratic costs, in: *Advances in Mathematics of Finance*, in: Banach Center Publ., vol. 104, Polish Acad. Sci. Inst. Math. Warsaw, 2015, pp. 9–24.
- [5] Ph. Briand, B. Delyon, Y. Hu, E. Pardoux, L. Stoica, L^p solutions of backward stochastic differential equations, *Stochastic Process. Appl.* 108 (1) (2003) 109–129.
- [6] P. Carr, T. Fisher, J. Ruf, On the hedging of options on exploding exchange rates, *Finance Stoch.* 18 (1) (2014) 115–144.
- [7] N. El Karoui, S. Peng, M.C. Quenez, Backward stochastic differential equations in finance, *Math. Finance* 7 (1) (1997) 1–71.
- [8] P.A. Forsyth, J.S. Kennedy, S.T. Tse, H. Windcliff, Optimal trade execution: a mean quadratic variation approach, *J. Econom. Dynam. Control* 36 (12) (2012) 1971–1991.
- [9] A. Friedman, *Stochastic Differential Equations and Applications*. Vol. 2, in: *Probability and Mathematical Statistics*, vol. 28, Academic Press, Harcourt Brace Jovanovich, Publishers, New York, London, 1976.
- [10] J. Gatheral, A. Schied, Optimal trade execution under geometric Brownian motion in the almgren and chriss framework, *Int. J. Theor. Appl. Finance* 14 (03) (2011) 353–368.
- [11] D. Gilbarg, N.S. Trudinger, *Elliptic Partial Differential Equations of Second Order*, in: *Classics in Mathematics*, Springer-Verlag, Berlin, 2001, Reprint of the 1998 edition.
- [12] P. Graewe, U. Horst, J. Qiu, A non-Markovian liquidation problem and backward SPDEs with singular terminal conditions, *SIAM J. Control Optim.* 53 (2) (2015) 690–711.
- [13] P. Graewe, U. Horst, E. Séré, Smooth solutions to portfolio liquidation problems under price-sensitive market impact, 2013. ArXiv e-prints.
- [14] D.S. Grebenkov, B.-T. Nguyen, Geometrical structure of Laplacian eigenfunctions, *SIAM Rev.* 55 (4) (2013) 601–667.
- [15] U. Horst, F. Naujokat, When to cross the spread? Trading in two-sided limit order books, *SIAM J. Financ. Math.* 5 (1) (2014) 278–315.
- [16] J. Jacod, *Calcul Stochastique et Problèmes de Martingales*, in: *Lecture Notes in Mathematics*, vol. 714, Springer, Berlin, 1979.

- [17] J. Jacod, A.N. Shiryaev, Limit Theorems for Stochastic Processes, second ed., in: Grundlehren der Mathematischen Wissenschaften [Fundamental Principles of Mathematical Sciences], vol. 288, Springer-Verlag, Berlin, 2003.
- [18] M. Jeanblanc, T. Mastrolia, D. Possamaï, A. Réveillac, Utility maximization with random horizon: a BSDE approach, *Int. J. Theor. Appl. Finance* 18 (7) (2015) 43. 1550045.
- [19] M. Jeanblanc, A. Réveillac, A note on BSDEs with singular driver coefficients, in: Arbitrage, Credit and Informational Risks, in: Peking Univ. Ser. Math., vol. 5, World Sci. Publ., Hackensack, NJ, 2014, pp. 207–224.
- [20] O. Kallenberg, Foundations of Modern Probability, Springer, Berlin, 2002.
- [21] J.B. Keller, On solutions of $\Delta u = f(u)$, *Comm. Pure Appl. Math.* 10 (1957) 503–510.
- [22] P. Kratz, T. Schöneborn, Portfolio liquidation in dark pools in continuous time, *Math. Finance* (2013).
- [23] T. Kruse, A. Popier, BSDEs with monotone generator driven by Brownian and Poisson noises in a general filtration, *Stochastics* (2015) <http://dx.doi.org/10.1080/17442508.2015.1090990>.
- [24] R. Osserman, On the inequality $\Delta u \geq f(u)$, *Pacific J. Math.* 7 (1957) 1641–1647.
- [25] É. Pardoux, S.G. Peng, Adapted solution of a backward stochastic differential equation, *Systems Control Lett.* 14 (1) (1990) 55–61.
- [26] H. Pham, Continuous-Time Stochastic Control and Optimization with Financial Applications, Vol. 61, Springer Science & Business Media, 2009.
- [27] R.G. Pinsky, Positive Harmonic Functions and Diffusion, in: Cambridge Studies in Advanced Mathematics, vol. 45, Cambridge University Press, Cambridge, 1995.
- [28] A. Popier, Backward stochastic differential equations with singular terminal condition, *Stochastic Process. Appl.* 116 (12) (2006) 2014–2056.
- [29] A. Popier, Backward stochastic differential equations with random stopping time and singular final condition, *Ann. Probab.* 35 (3) (2007) 1071–1117.
- [30] M.-C. Quenez, A. Sulem, BSDEs with jumps, optimization and applications to dynamic risk measures, *Stochastic Process. Appl.* 123 (8) (2013) 3328–3357.
- [31] A. Schied, A control problem with fuel constraint and Dawson–Watanabe superprocesses, *Ann. Appl. Probab.* 23 (6) (2013) 2472–2499.